

Local-to-Global Algorithms in Biology: *Drosophila* and Beyond (maybe ...)

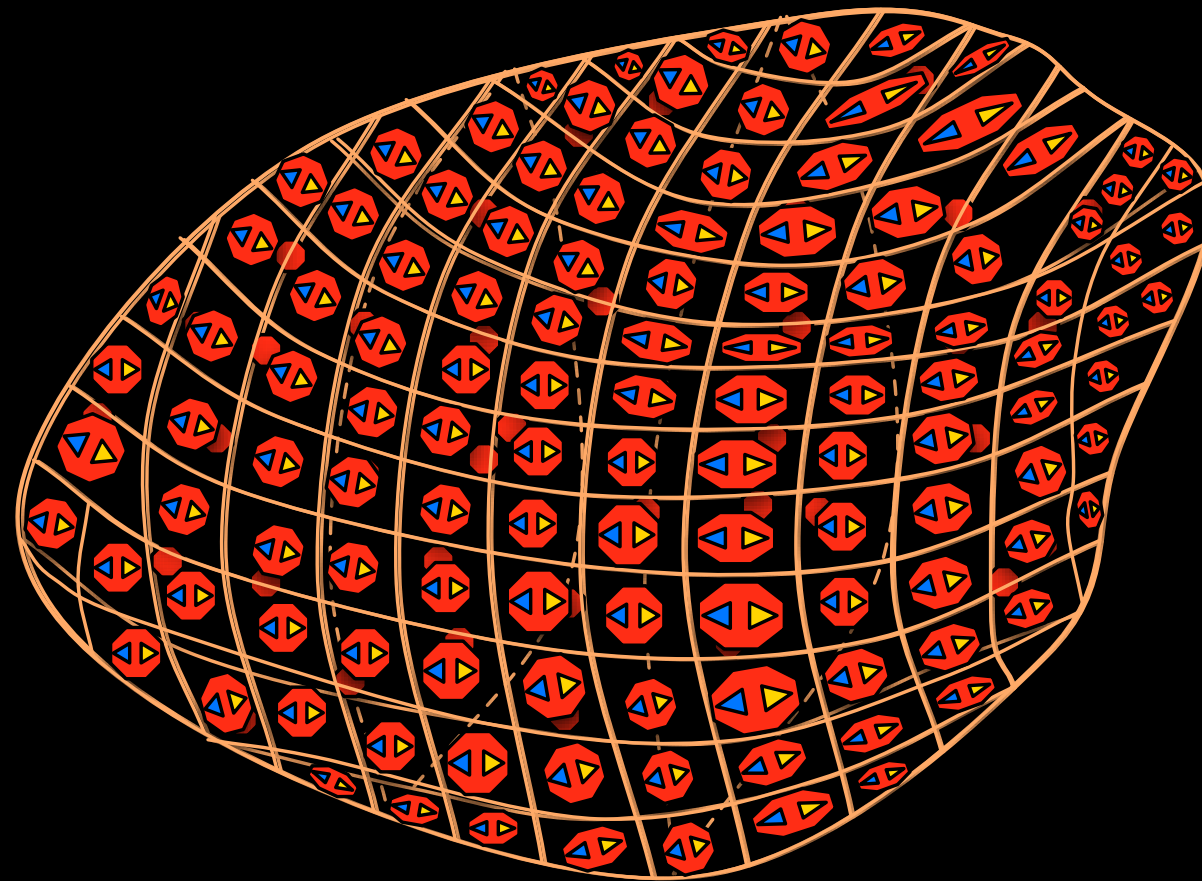
MIT Synthetic Biology Working Group

Dan Yamins

2007.12.05

spatial multi-agent systems

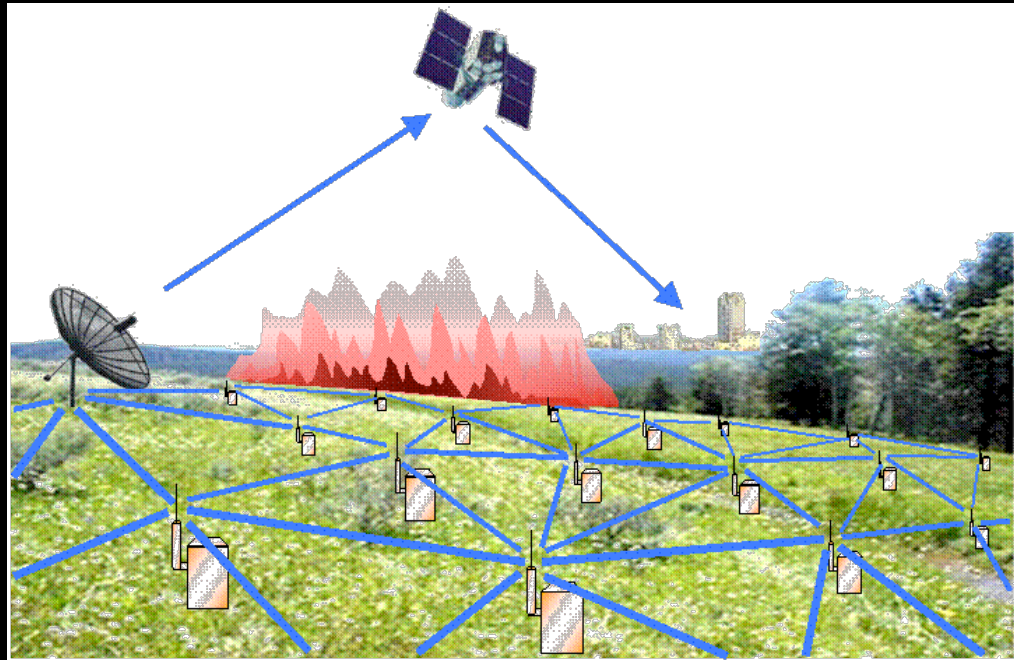
a space with agents embedded in the space



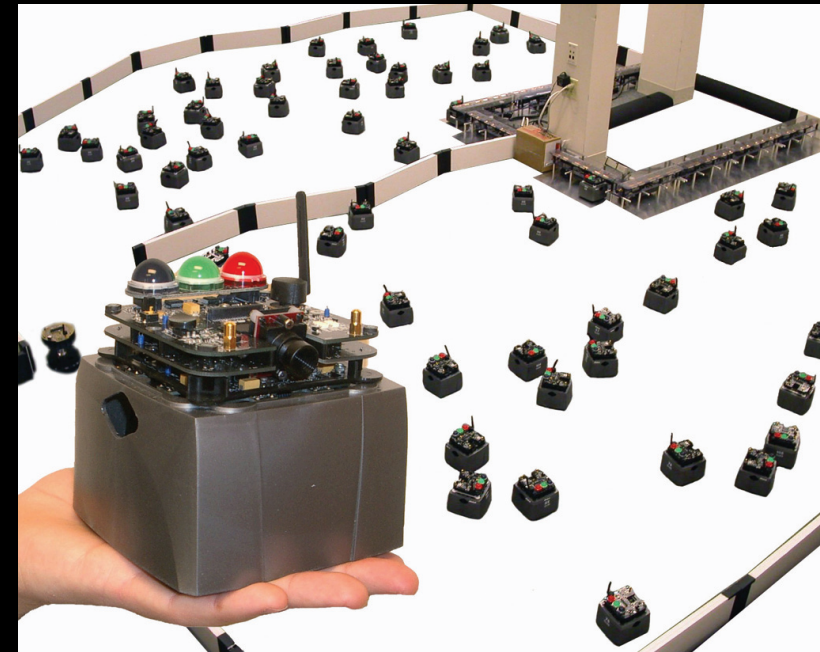
local information and processing

globally defined tasks

engineering:



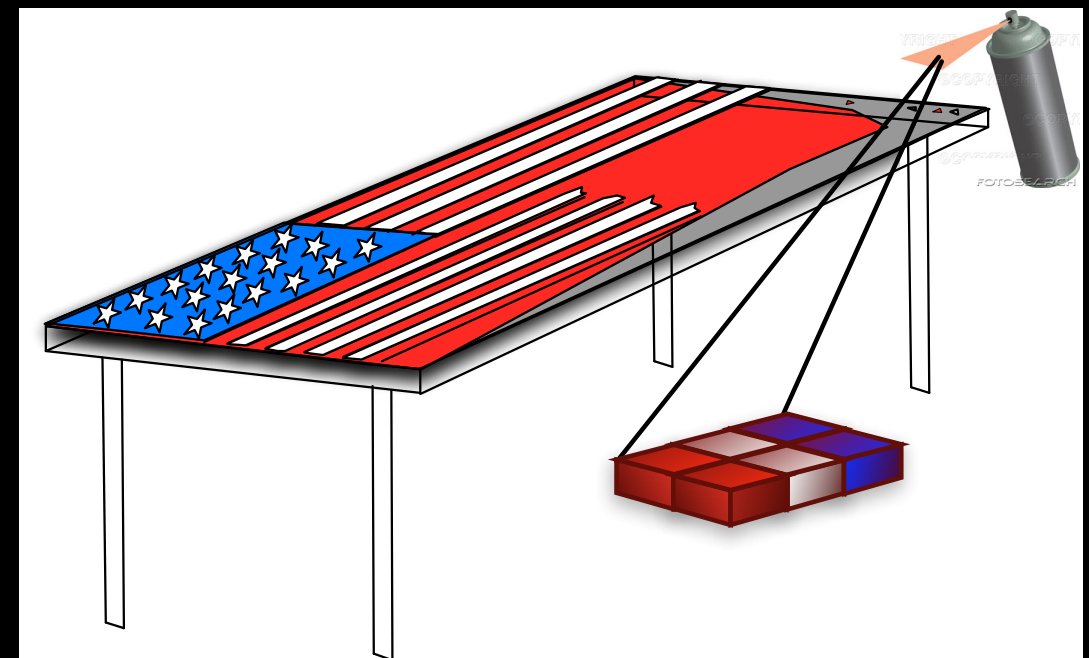
Sensor Networks



McLurkin iRobot Swarm

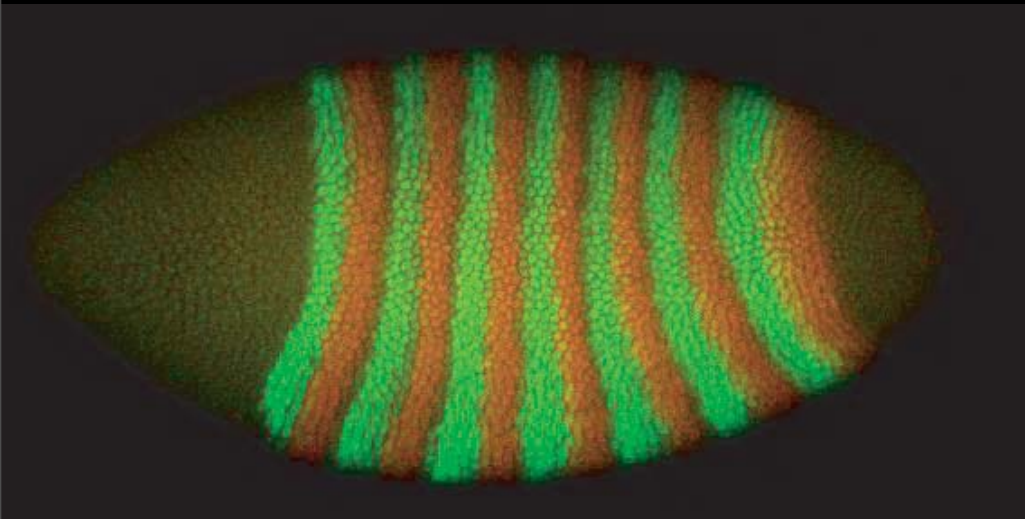


Saul Griffith's self-folding structures

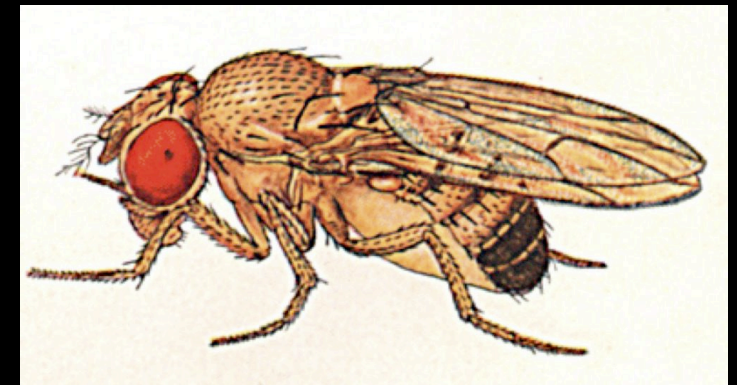


Butera's "paintable computer" concept

biology:



drosophila embryo



- What does thinking of natural spatial multi-agent systems *qua* computers tell us scientifically?
- What agent resource capacities are required to solve a given task?
- Can we then turn around this knowledge to build a better bug?

outline

I. *Drosophila* background

II. Multi-agent systems Model of *Drosophila*

III. An information bound

IV. The Radius/State Tradeoff

The first four sections study a known system, showing how multi-agent systems reasoning can help us understand features of local-to-global systems design.

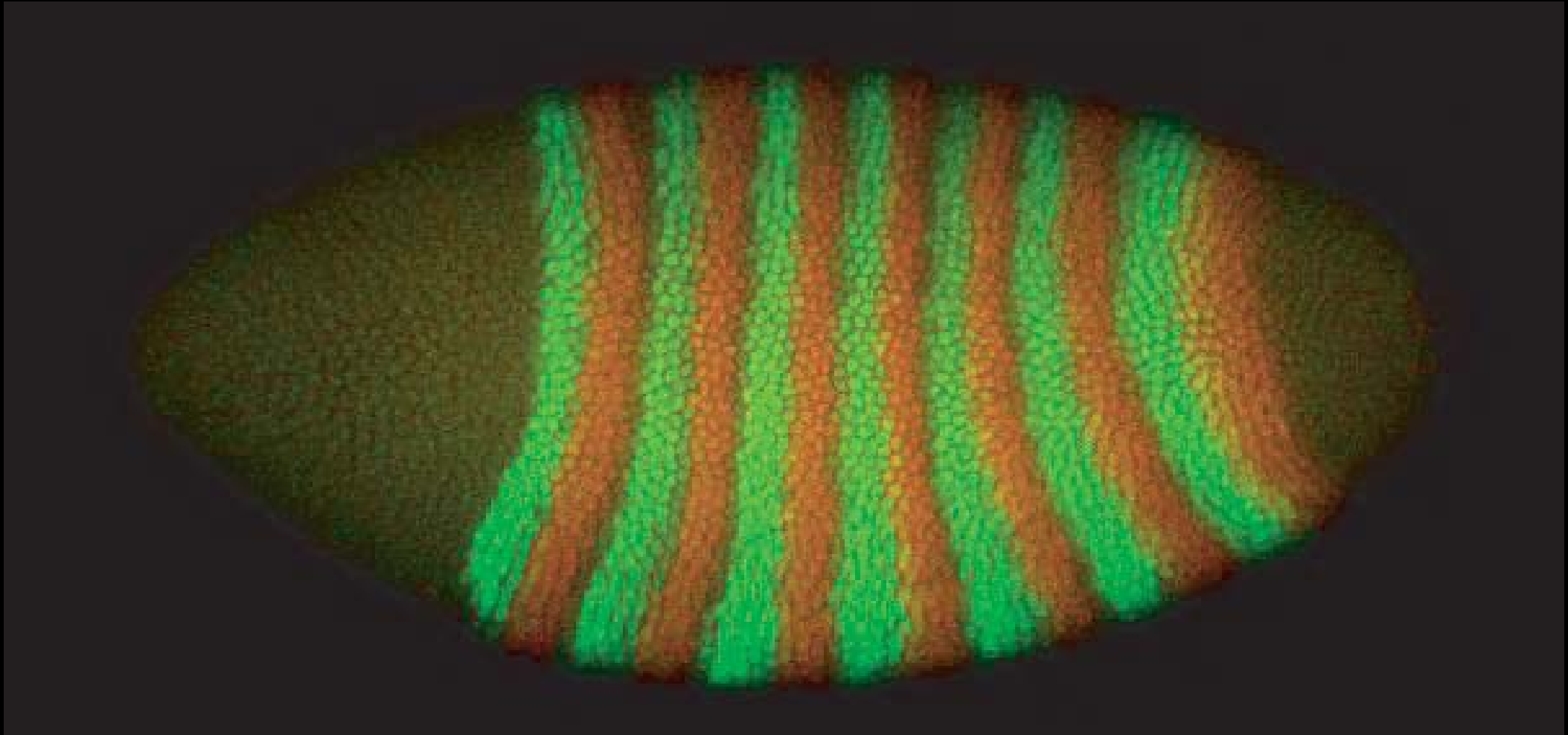
V. Designing Local Rules

The fifth section takes this knowledge, and applies it to develop the beginnings of a protocol for designing novel systems.

Drosophila Background

(Actually ... one stage
in early *Drosophila*,
utterly simplified)

Drosophila



Drosophila melanogaster embryo
about 100 minutes post-fertilization

Drosophila

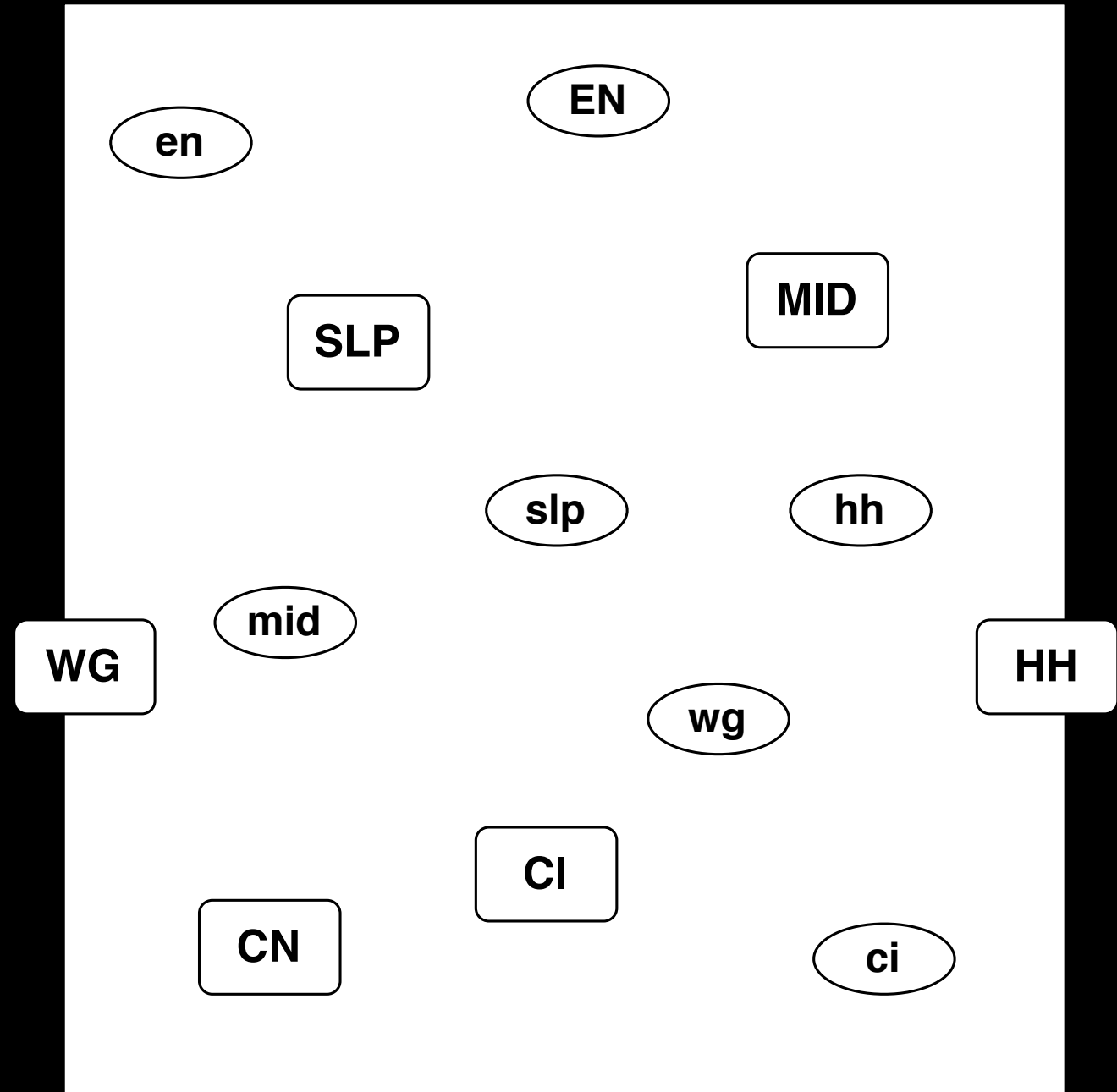
Let's think of
the cell as a

.... bag of
biomolecules

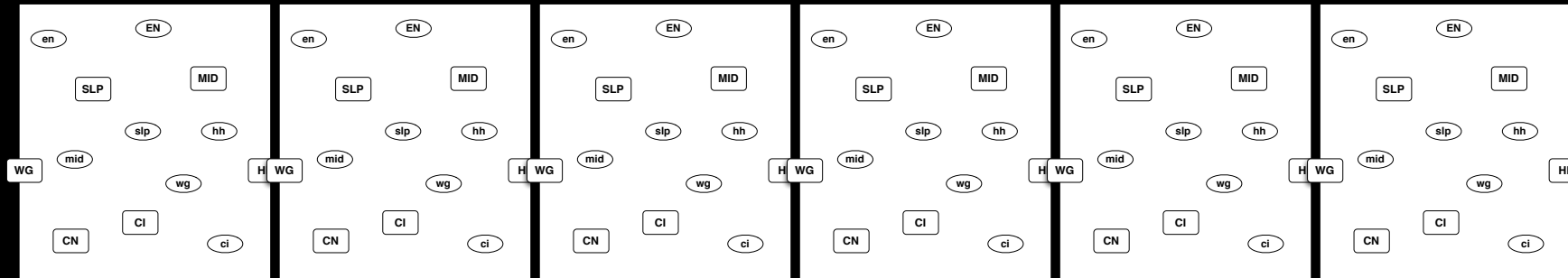
Highlighted here are
13 substances that
play are involved in
the stripes in the
picture on the
previous slide

PROTEIN

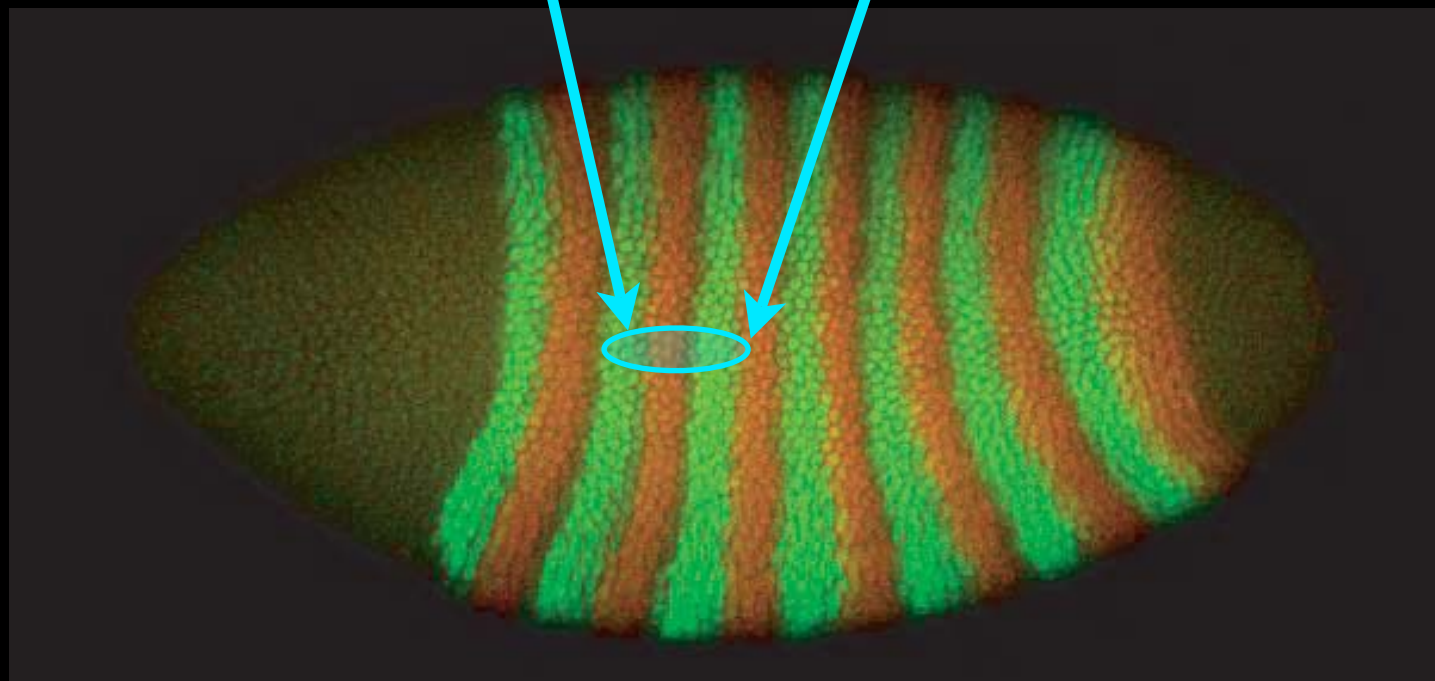
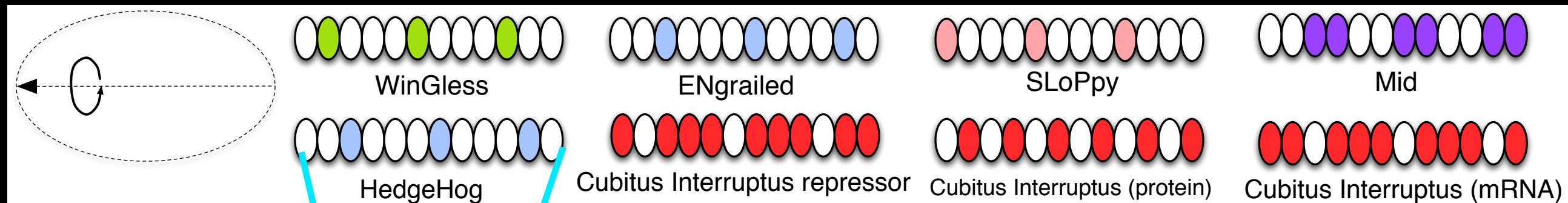
mRNA



Considering cells along the A-P axis:



... there is a periodic pattern in the concentration of each of various substances depicted on the previous slide:

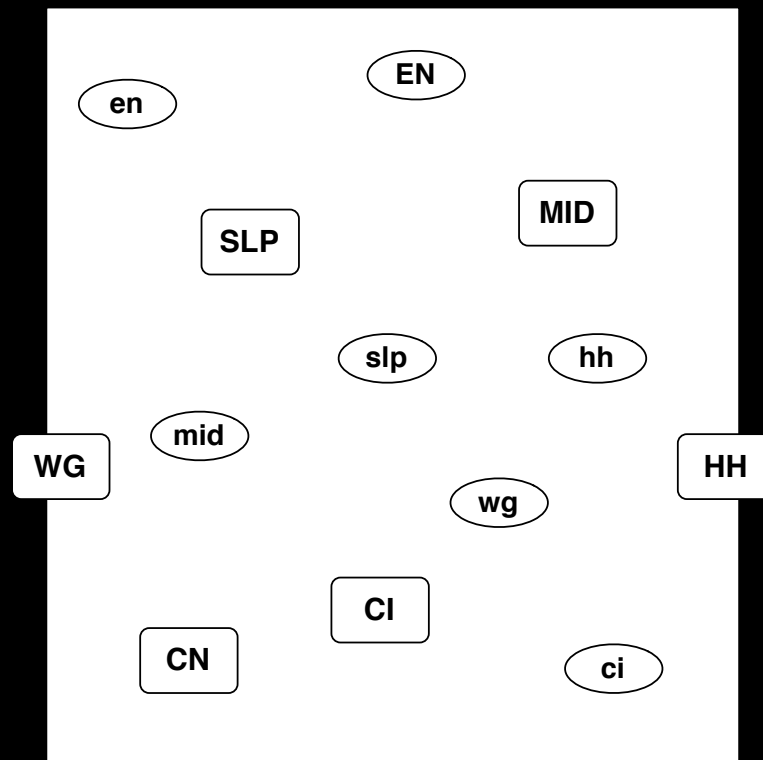


The concentration profile pattern at the molecular level corresponds the observed stripe pattern.

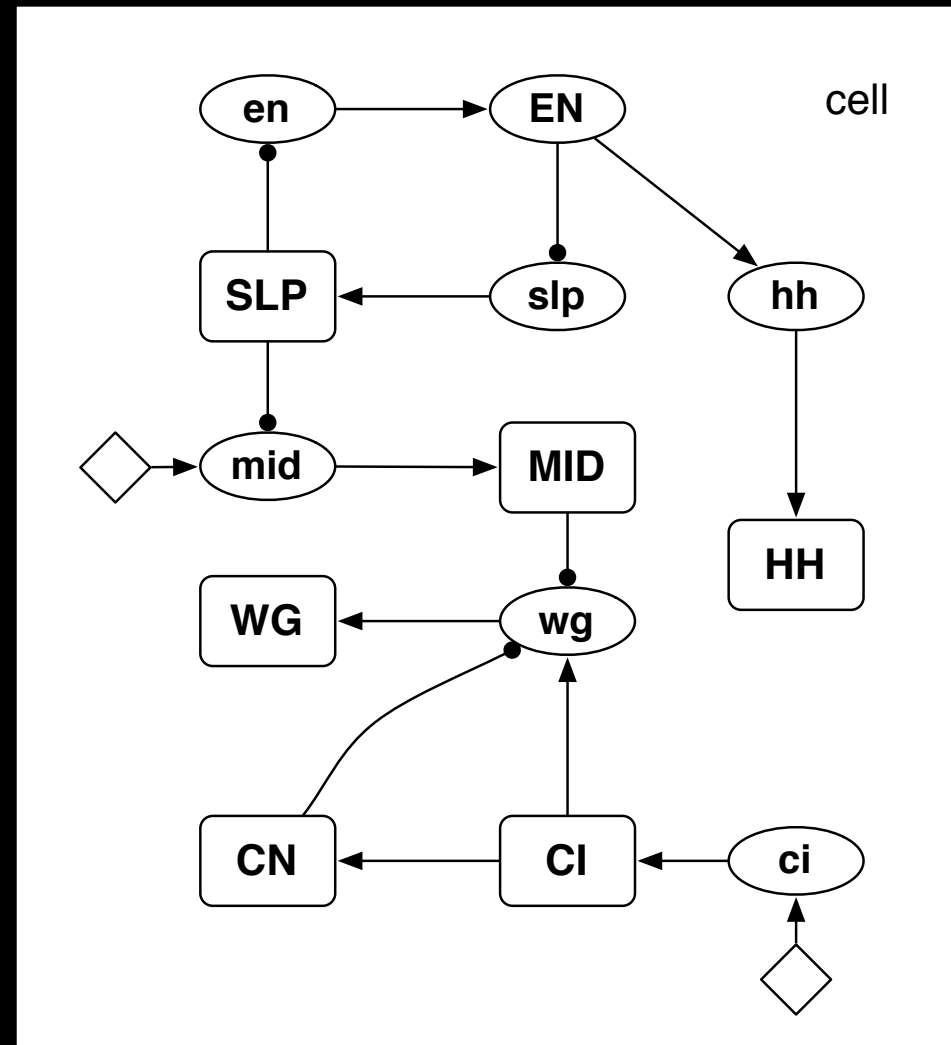
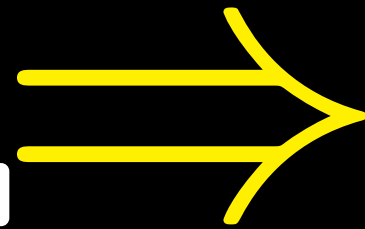
Drosophila

PROTEIN

mRNA



The bag of biomolecules ...

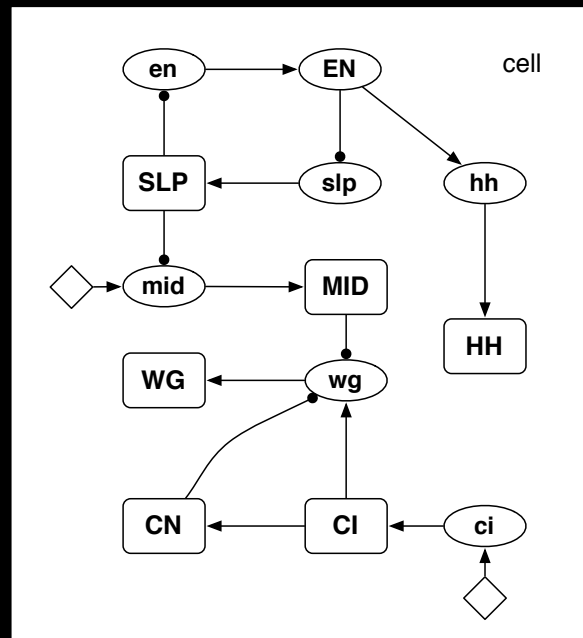


... is actually a Gene Regulatory Network

Positive Induction →

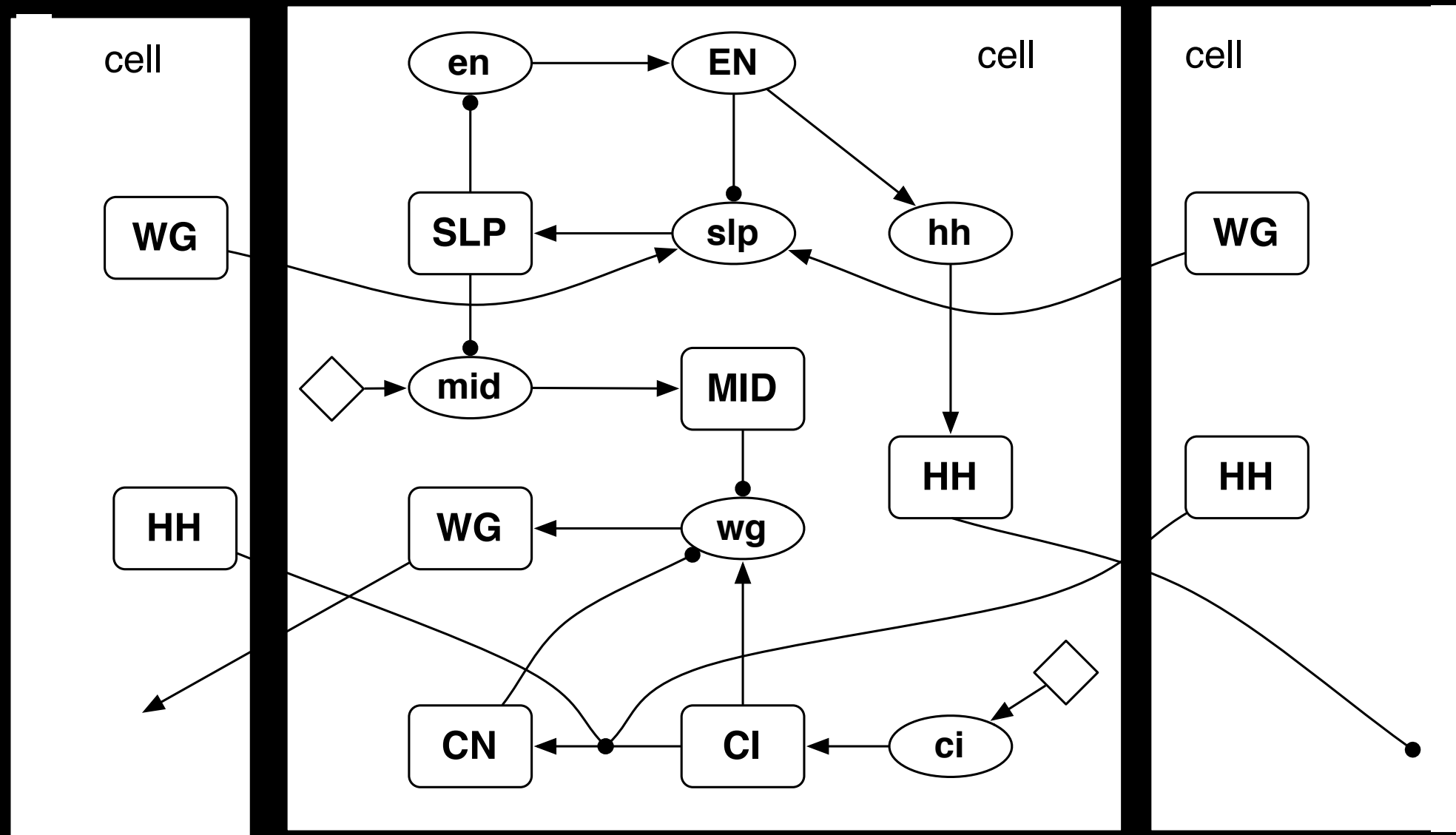
Negative Inhibition •

Basal Production
◇ →

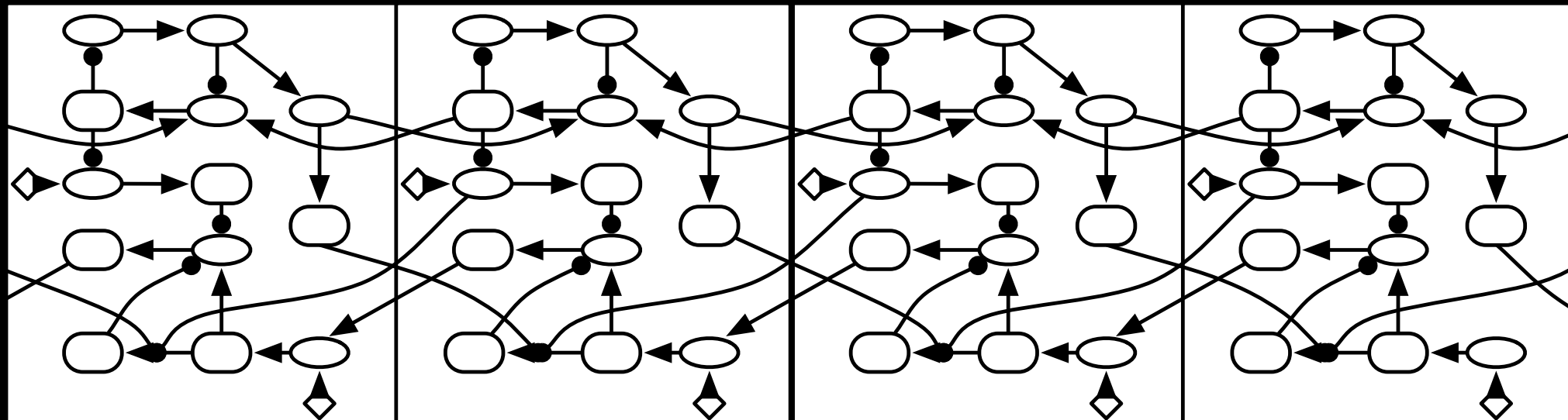


Some components of the Gene Regulatory Network in one cell ...

... influence those in neighboring cells.



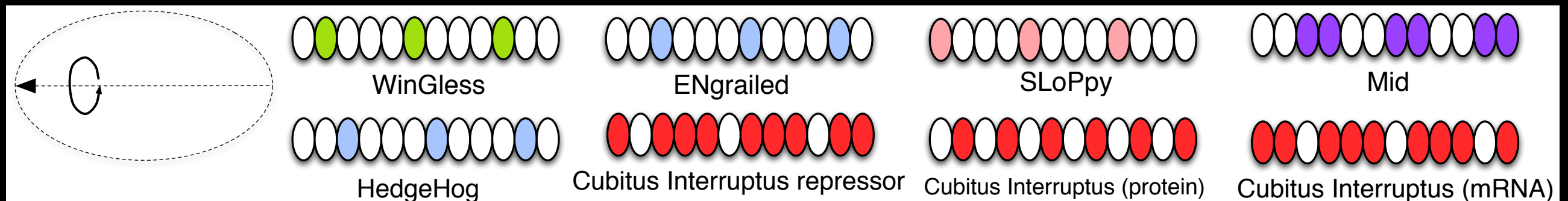
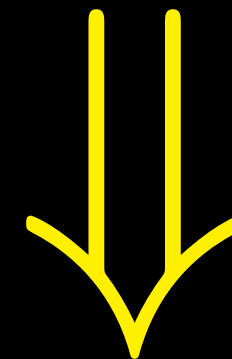
It's a spatially coupled Gene Regulatory Network.



Such a network can be modeled as a coupled ODE:

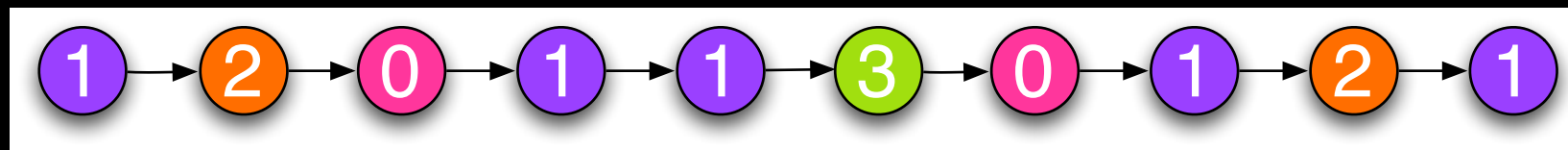
$$\frac{dS_j^i}{dt} = f_j \left(S_1^i, S_2^i, \dots, S_N^i, S_1^{i-1}, S_2^{i-1}, \dots, S_N^{i-1}, S_1^{i+1}, S_2^{i+1}, \dots, S_N^{i+1} \right)$$

And the ODE will (a la Garrett Odell)
have the pattern as a *stable
nondegenerate steady state*:



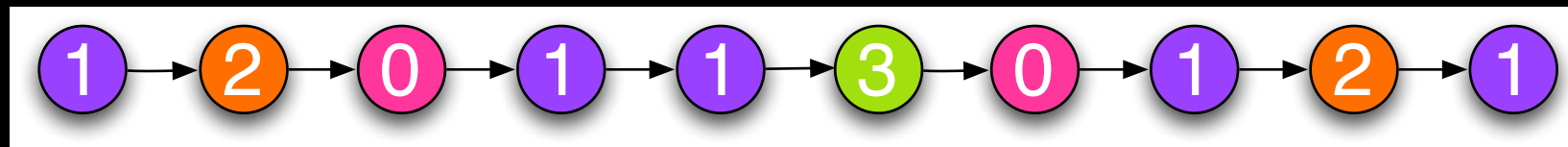
a multi-agent model of drosophila

(a *sketchy* multi-agent model of
drosophila)

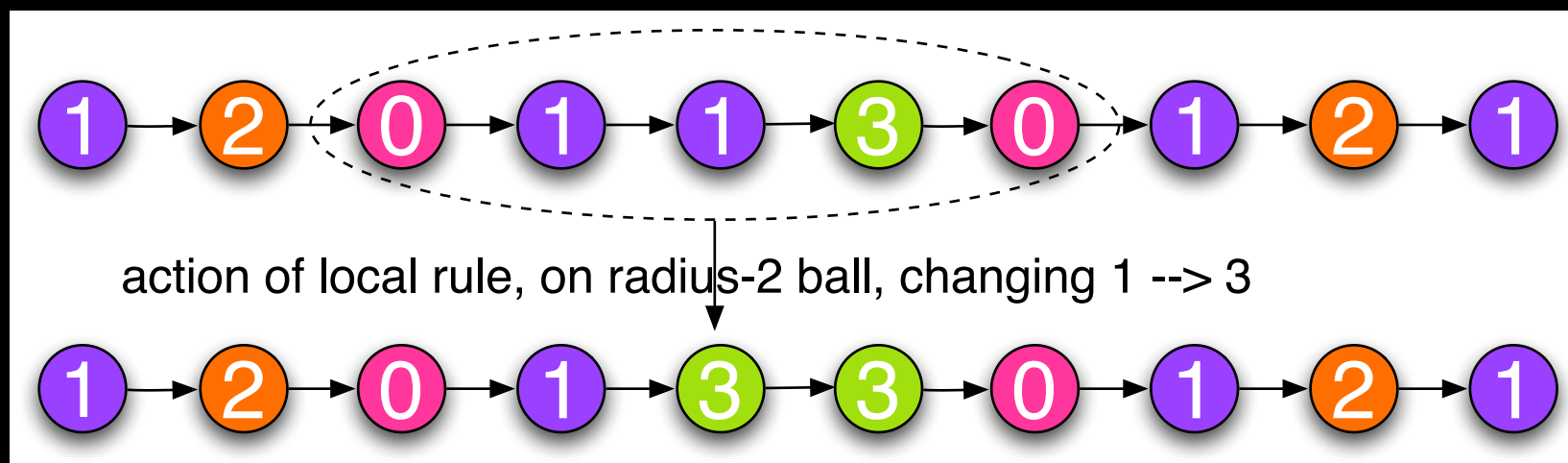


... a simple “I-D” organism, each cell of which
has some internal state (0, 1, 2, 3, etc...)

multi-agent model



local rules by which the agent integrates
information about states of nearby agents
and takes a differentiation action



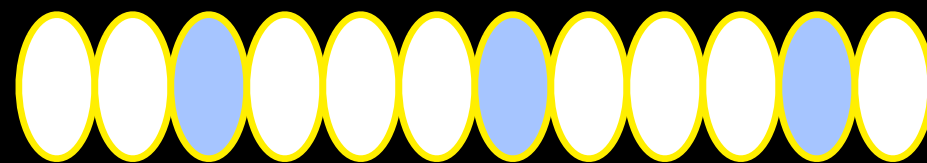
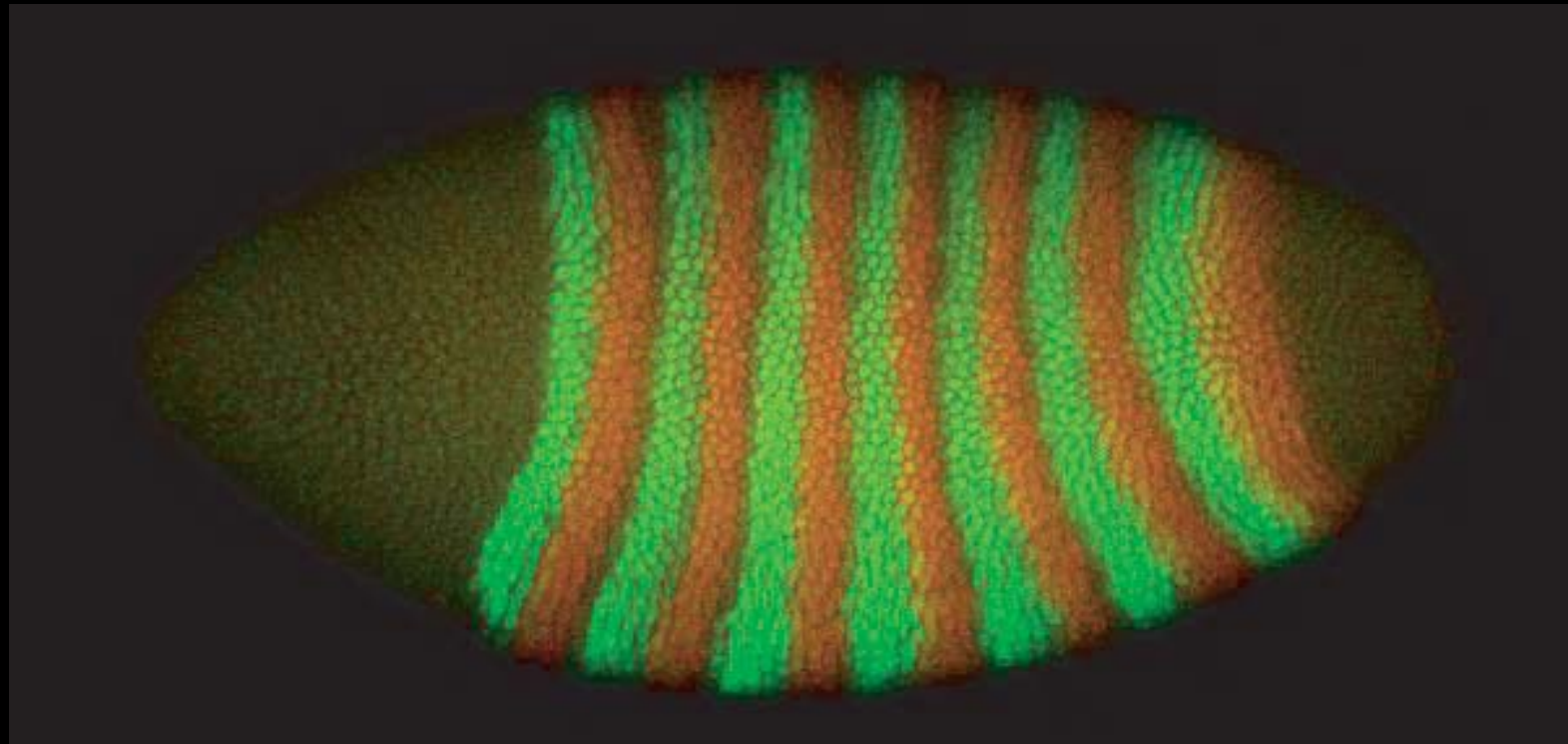
any radius-1 (nearest neighbor) local rule
is allowed.

multi-agent model

1 → 0 → 0 → 0 size 4 instance

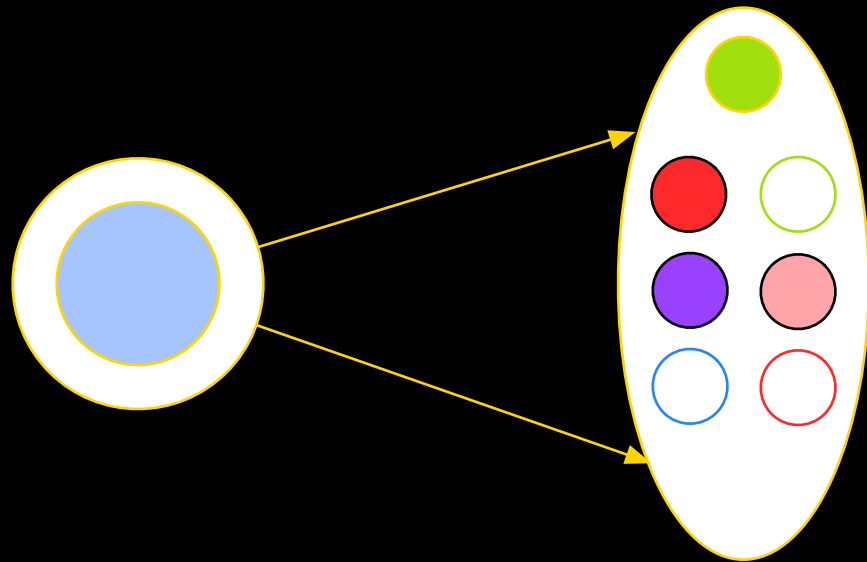
1 → 0 → 0 → 0 → 1 → 0 → 0 → 0 size 8 instance

1 → 0 → 0 → 0 → 1 → 0 → 0 → 0 → 1 → 0 → 0 → 0 size 12 instance



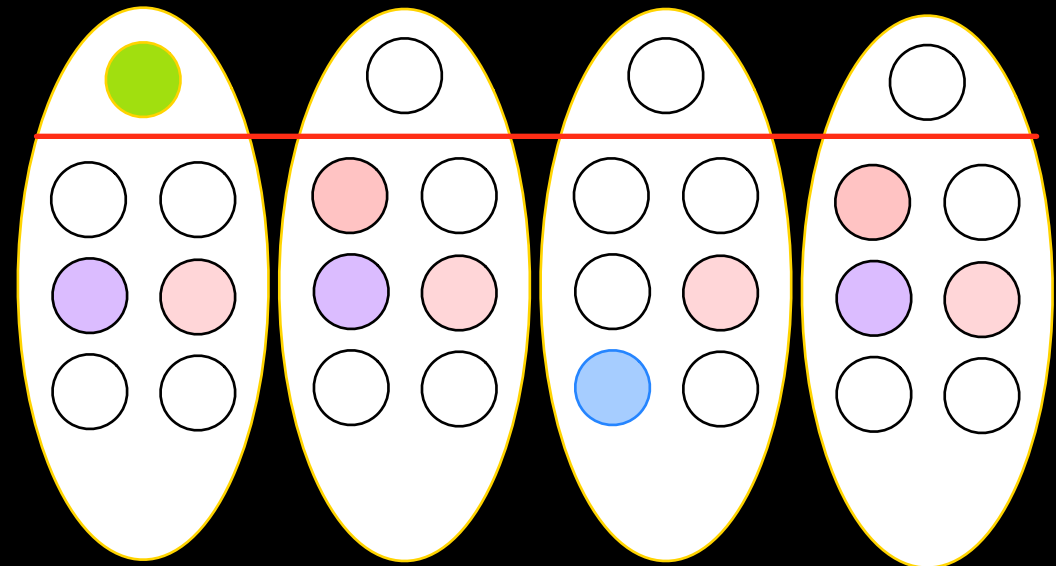
ENgrailed

multi-agent model

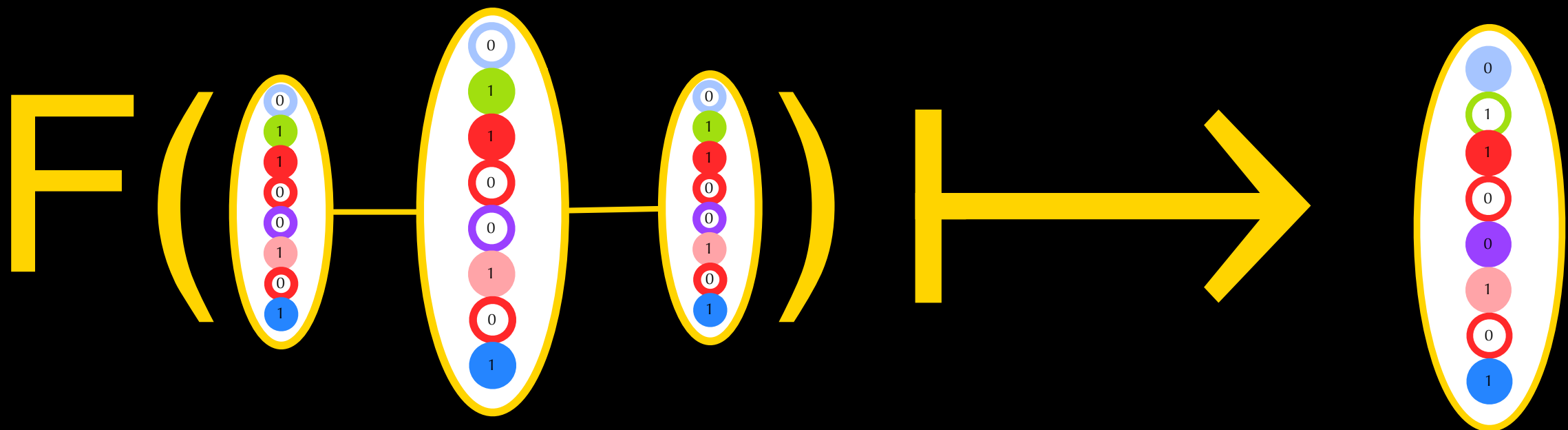


Agent with unstructured internal state.

Add “slots.”

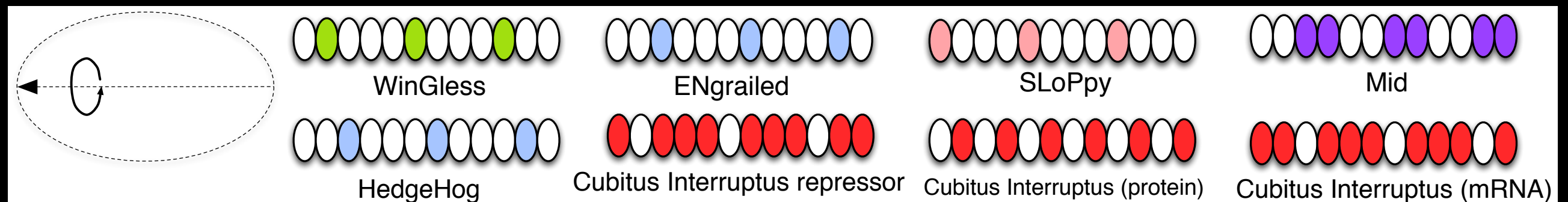
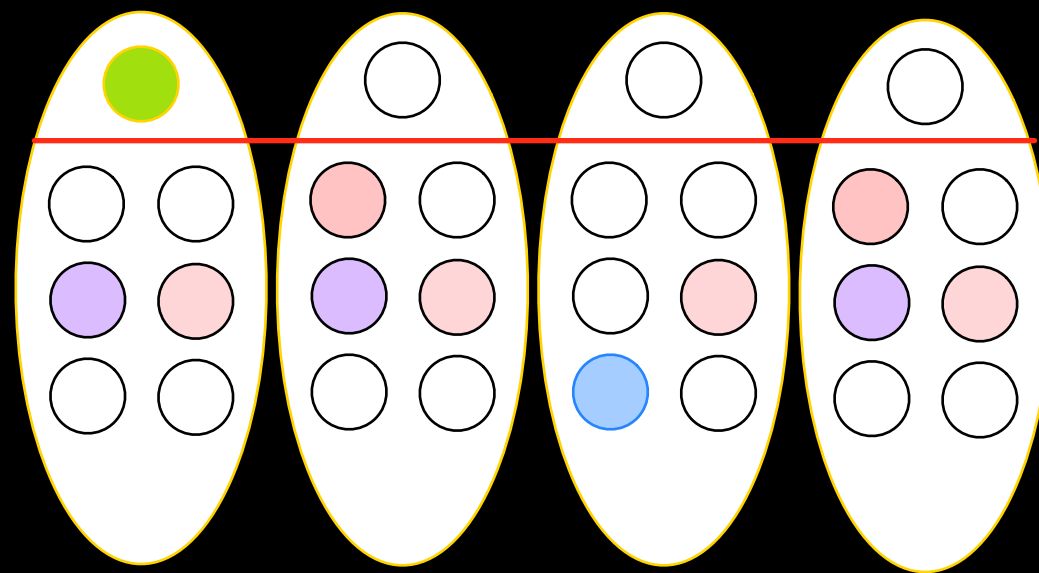
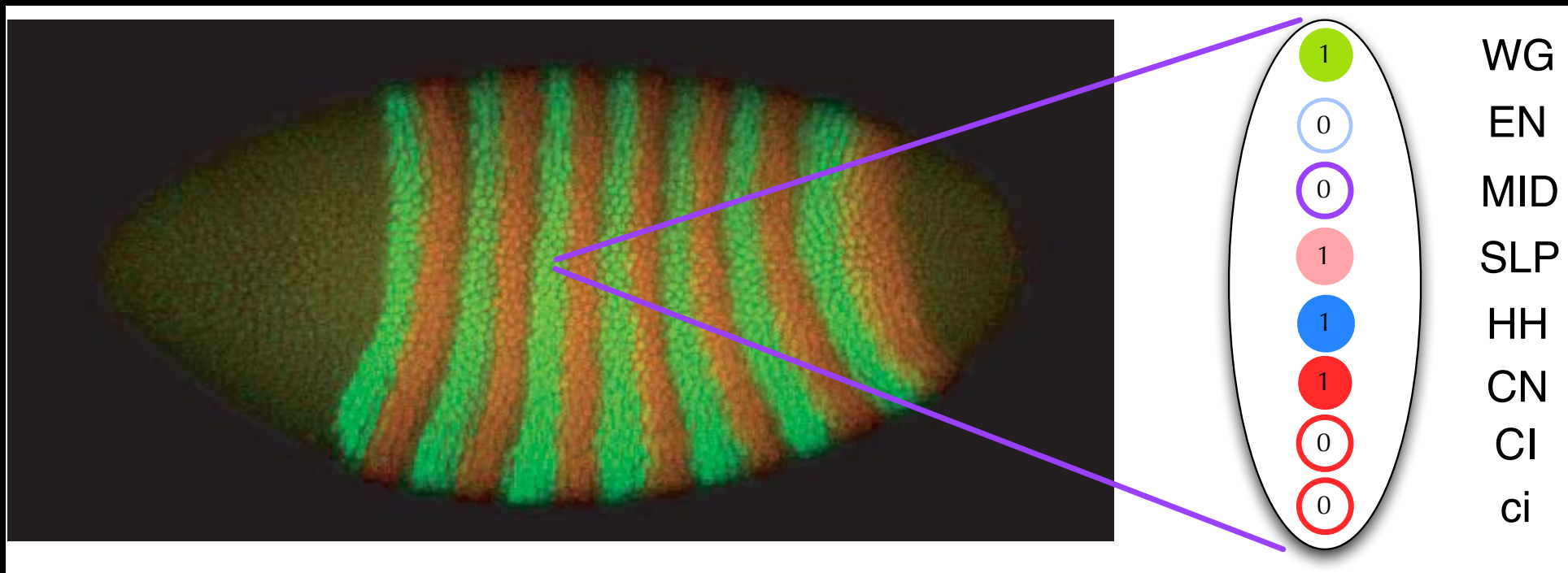


Structured “multi-register” internal states.

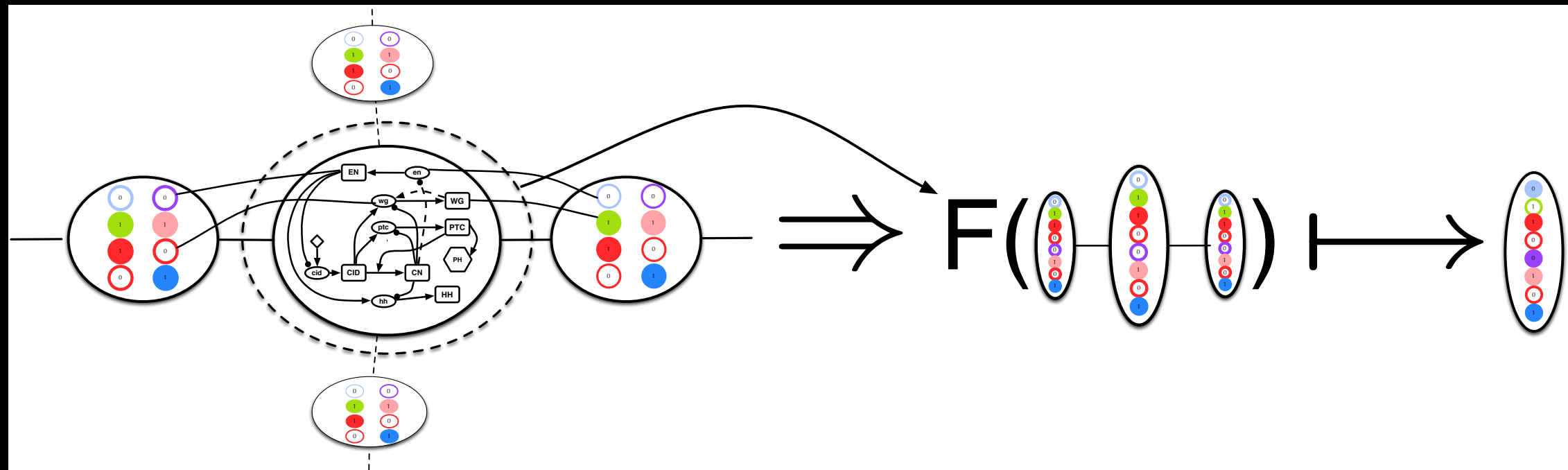


Multislot dynamics

multi-agent model



multi-agent model



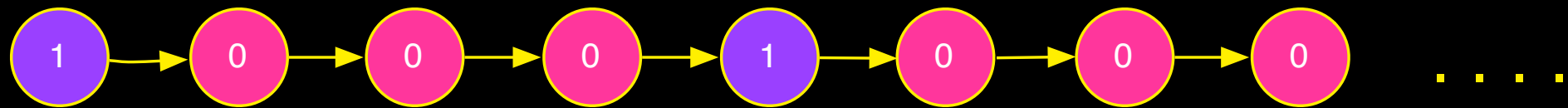
the gene regulatory network
as a nearest-neighbor local rule

the “brains” of the cellular-agent

An
informational
bound

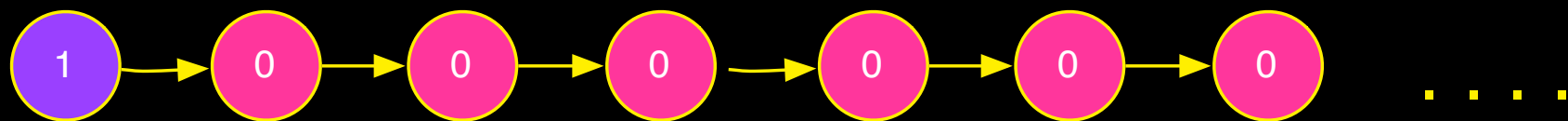
Local Checkability

Consider the repeat pattern:



Can this pattern be solved robustly with a nearest-neighbor rule?

Answer: No. Because the with a radius 1 rule, 000 would have to be a fixed state.

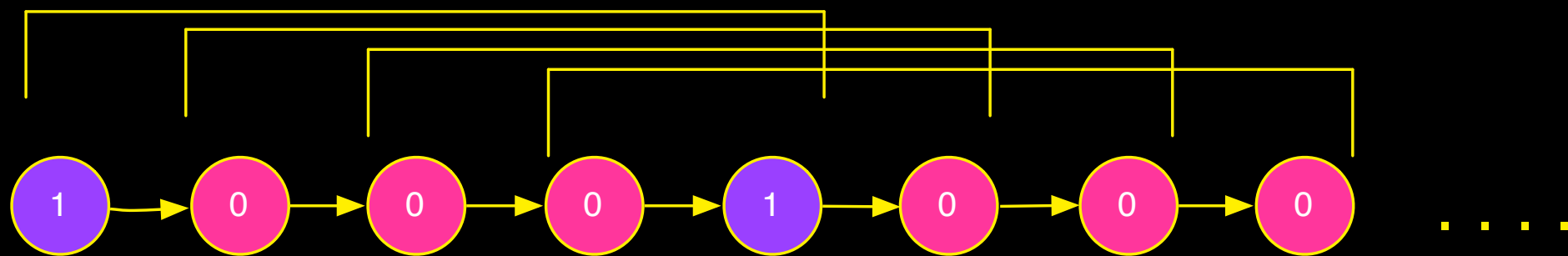


local checkability; multi-agent reasoning about local equilibria

A function $\Theta : B_r \rightarrow \{0, 1\}$ is a *local check scheme* for a pattern T if

$$\bigwedge_{i \leq |X|} (\Theta(B_r(i, X)) = 1) \Rightarrow X \in T$$

This means: if all cells think “criterion Theta” is true ... then actually the organismal pattern is correct



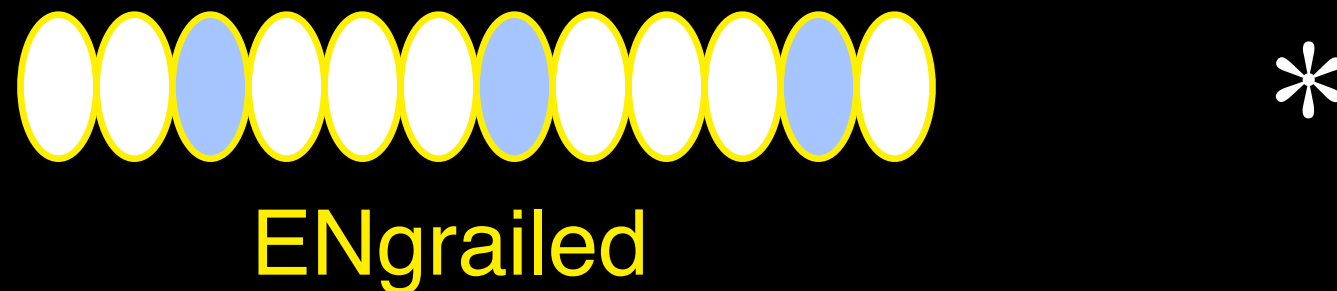
1000 has a radius-2 check scheme.

All repeated patterns are locally checkable.

Any pattern thus has a *minimal* check radius, a lower bound on how far local rules have to see to form the pattern robustly.

local checkability; multi-agent reasoning about local equilibria

Hey. Wait.



Local check radius of this pattern is $= 2$, and in fact to actually make a rule radius $5/2$ is required.

But the coupled gene network rules are nearest neighbor (i.e. $r = 1$).

Put another way, no equation of the form:

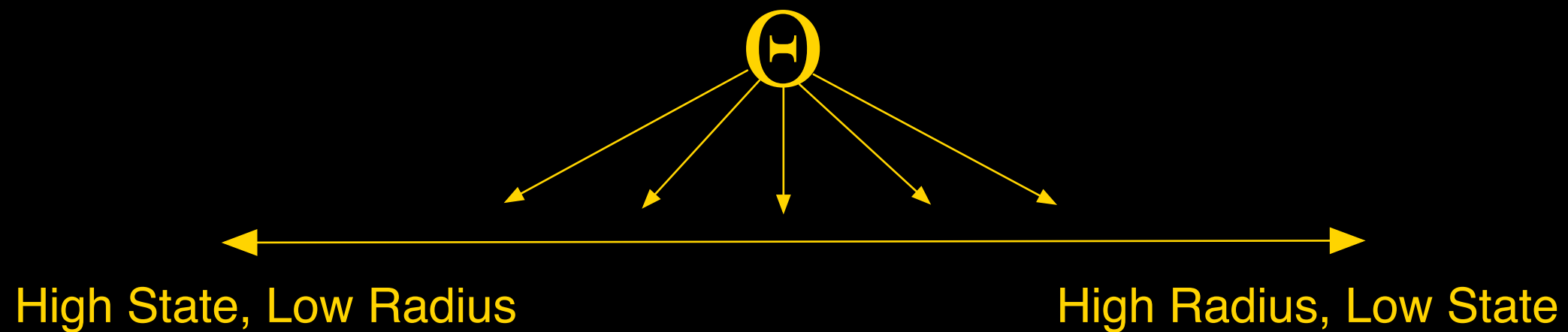
$$\frac{dS_j^i}{dt} = f_j (S_1^i, S_2^i, \dots, S_N^i, S_1^{i-1}, S_2^{i-1}, \dots, S_N^{i-1}, S_1^{i+1}, S_2^{i+1}, \dots, S_N^{i+1})$$

can have a nondegenerate stable steady state of the form * if engrailed is decoupled.

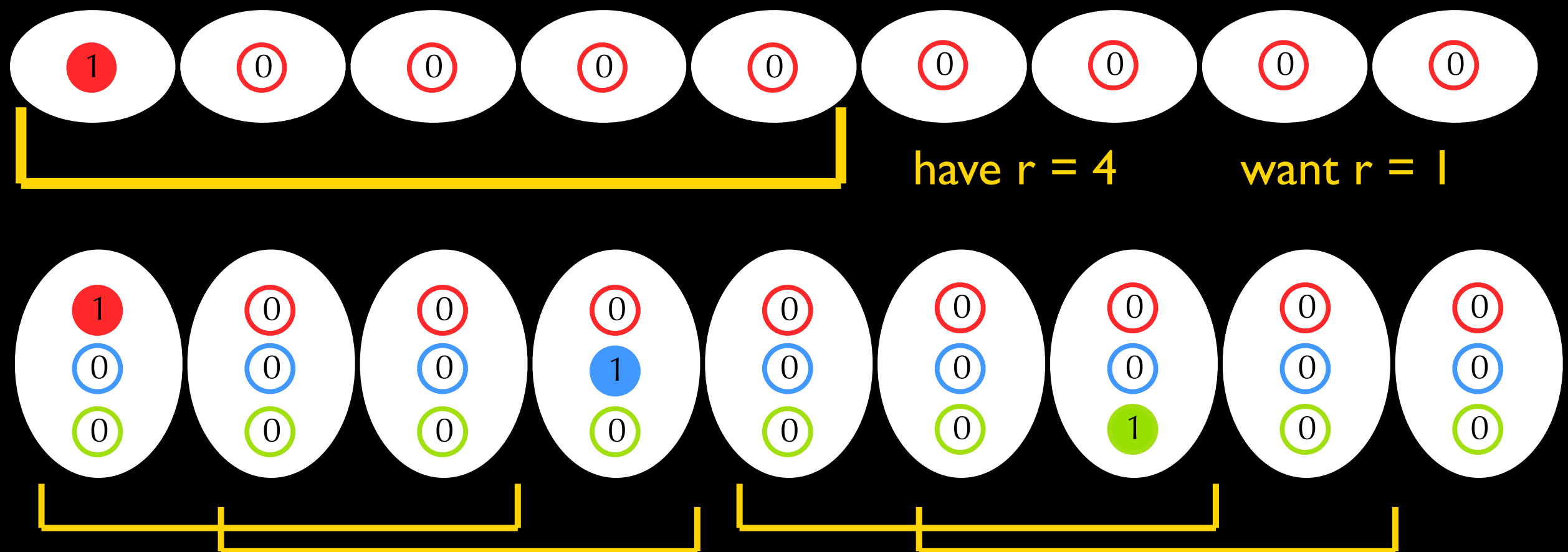
The system is “trying” to make a 4-coordinate....

The Radius/State Tradeoff

The Radius/State Tradeoff



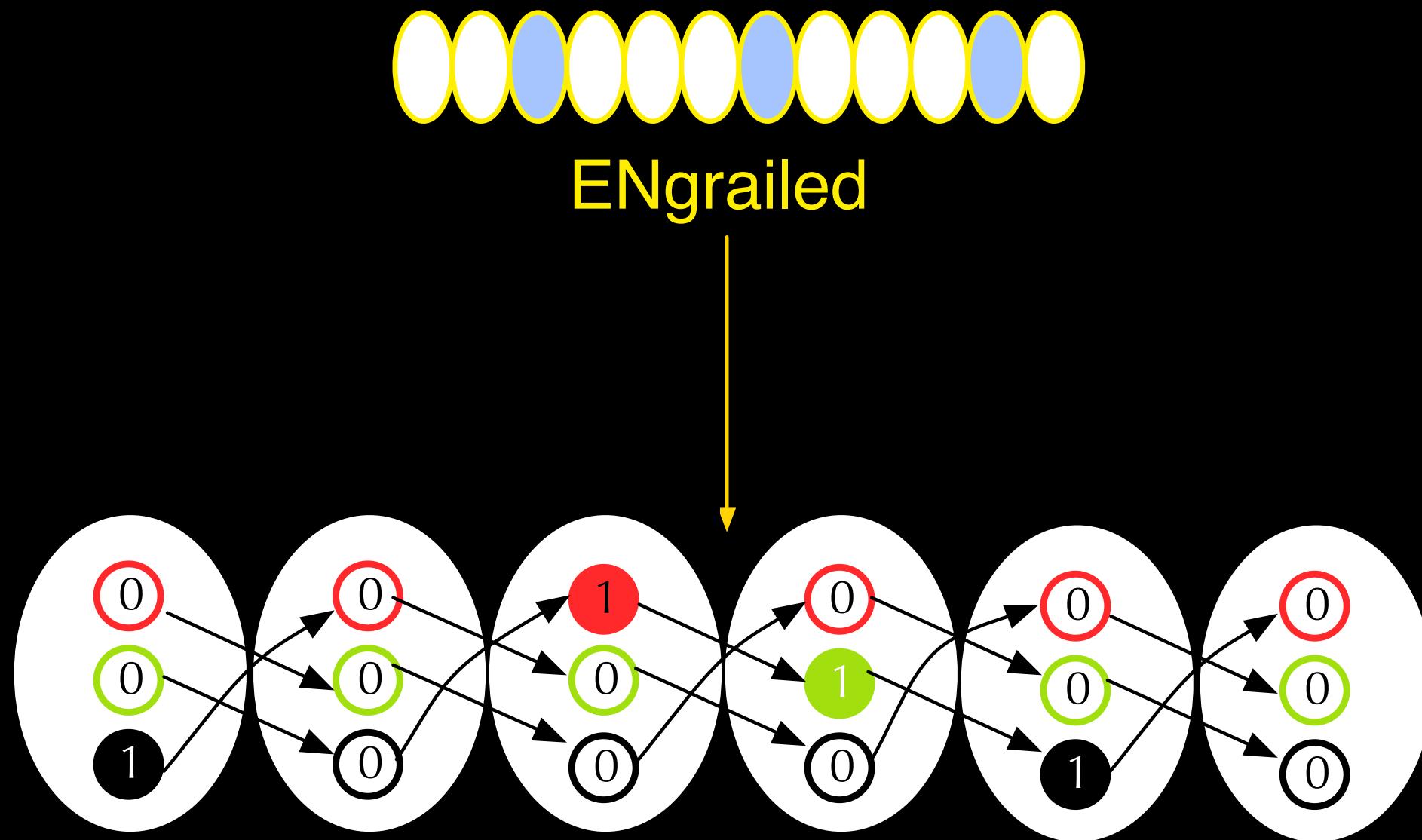
A generic “cut-and-shift” procedure for implementing the Radius \rightarrow tradeoff:



#slots = $\lceil (2r + 1) / (2k + 1) \rceil$ to go from radius r to radius k .

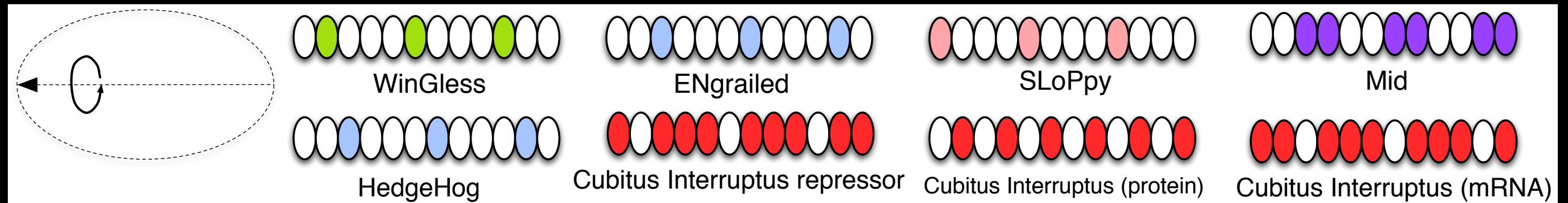
The Radius/State Tradeoff

Let's apply radius/state tradeoff "cut-and-shift" procedure.

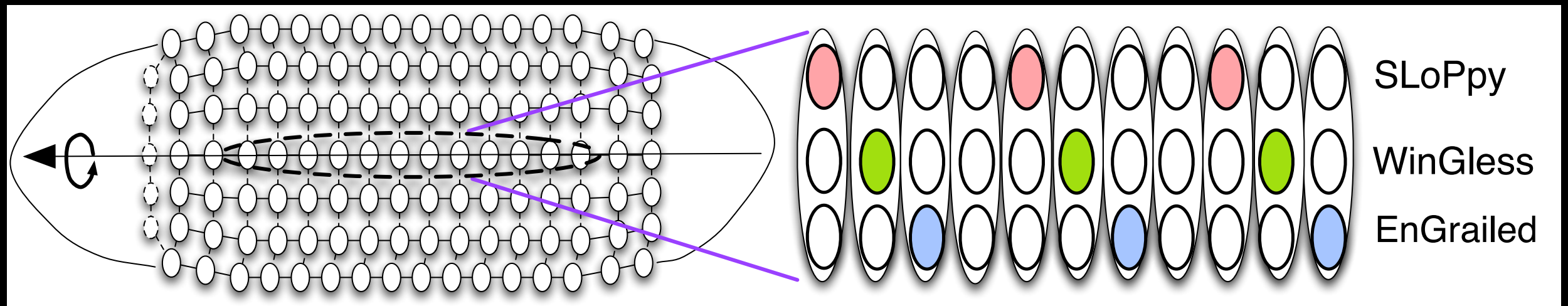


To get a make the trade, the algorithm adds two extra "slots."

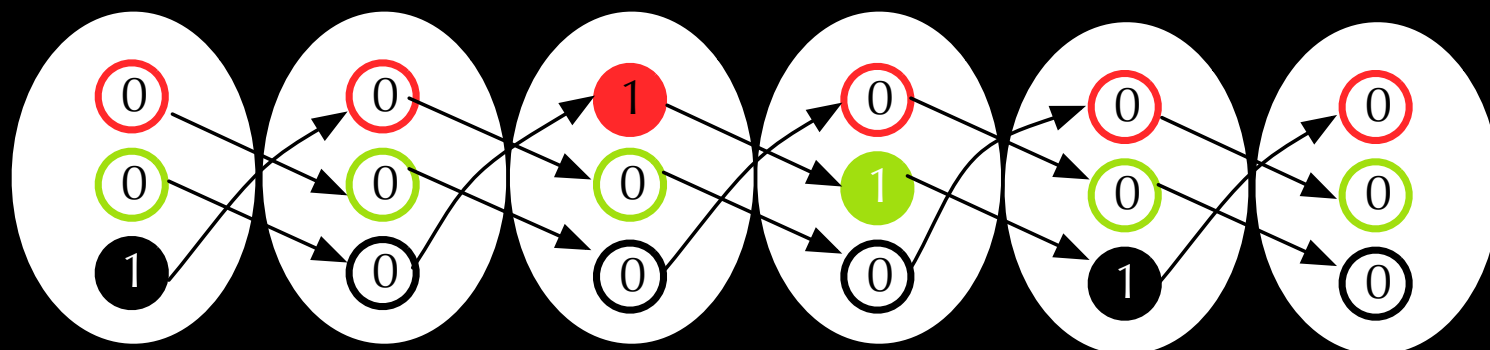
The Radius/State Tradeoff



Focus on the three proteins: Sloppy, Wingless, Engrailed.

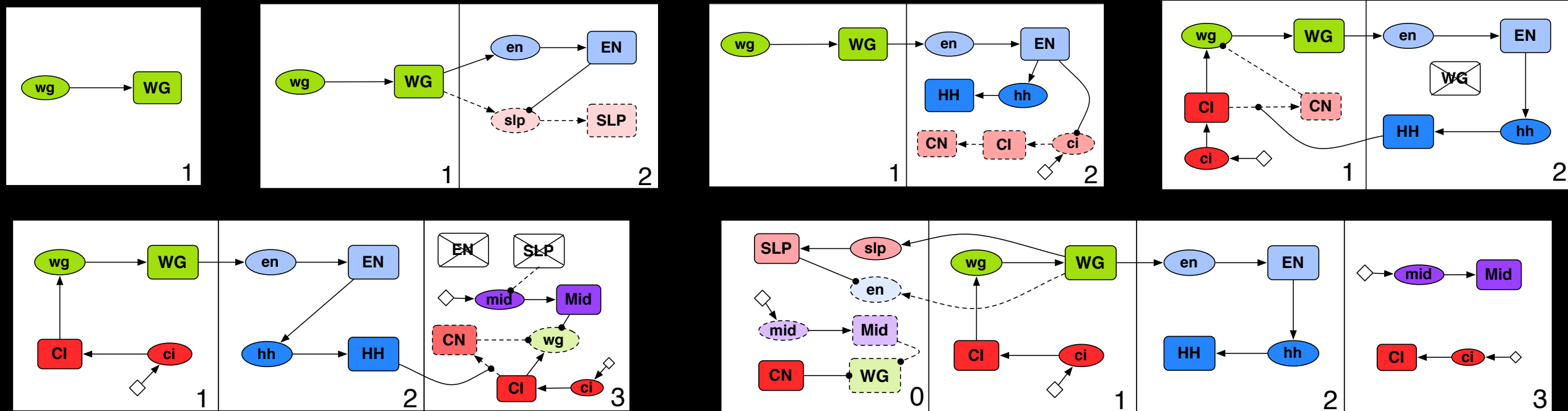


Interesting superficial resemblance:

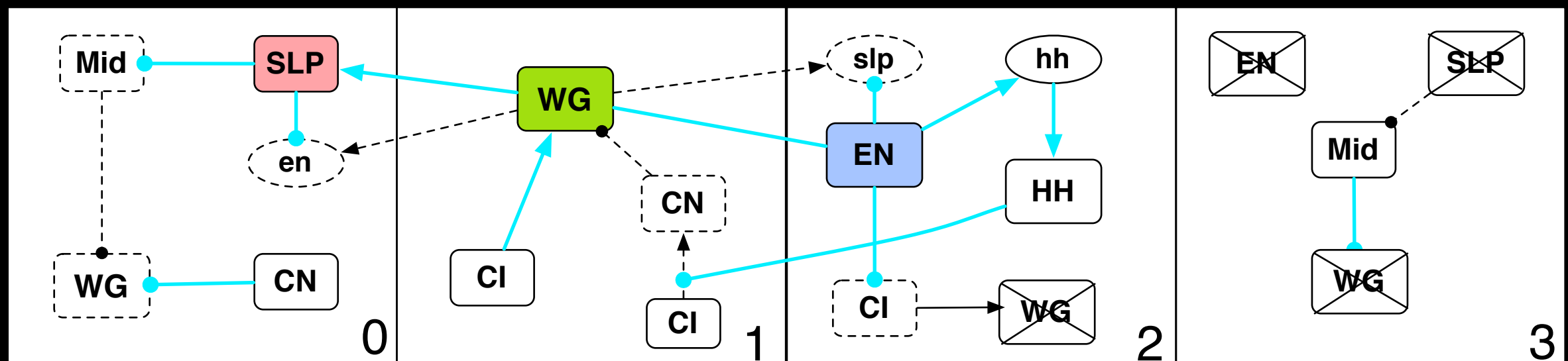


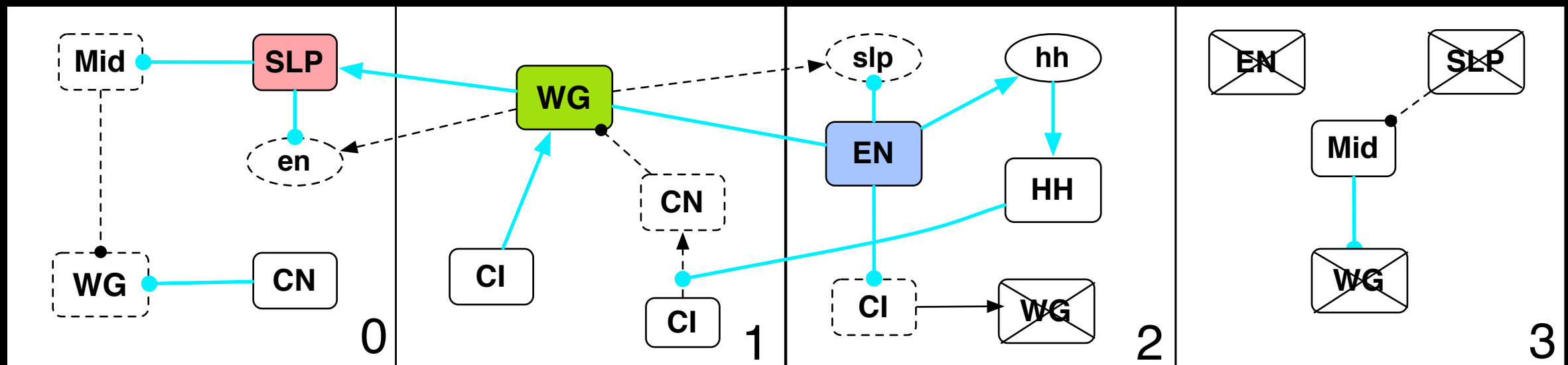
The Radius/State Tradeoff

Much stronger form of validation comes by isolating a “path” within the gene regulatory network that stabilizes the three proteins in a spatial feedback sequence:

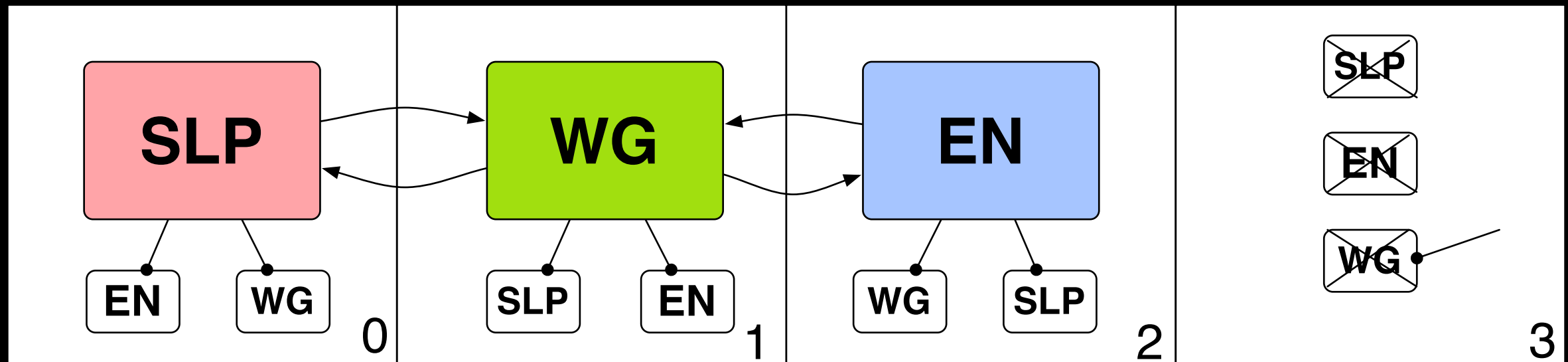


The dynamically activated subnetworks:





Consolidating the intermediates:



Conclusion: the coordination of multiple input-output state relations that unfold over space and time allow cellular agents with nearest-neighbor views to generate long-range coordinate patterns.

Experimental: look in related drosophilids for modifications (DePace lab)

Beyond
Drosophila
(kinda, sorta, *maybe*)

- What does thinking of natural spatial multi-agent systems *qua* computers tell us scientifically?

It tells about local information requires, helping understand:

- What agent resource capacities are required to solve a given task.

But the things we learned (i.e. cut and shift) were general.

- Can we then turn around this knowledge to build a better bug?

so that we could, for example, make general patterns?

In theory.

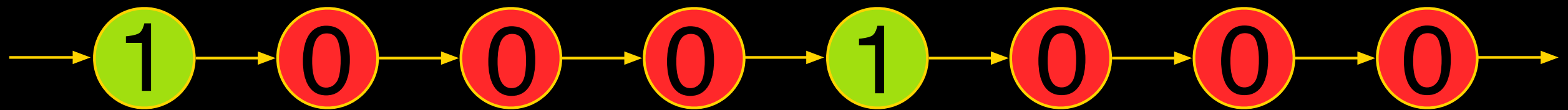
Designing Local Rules

Goal: Design local rules to make given patterns.

Repeat patterns have a well-defined gradient.

$$\nabla_{\Theta}(B)^+ = \begin{cases} i, & \text{if } B \circ i \text{ is consistent with } \Theta \\ B(2R), & \text{otherwise} \end{cases}$$

For example: 1000-repeat pattern (which has an $r = 2$ check scheme),



$$\nabla_{\Theta}(100)^+ = 0$$

$$\nabla_{\Theta}(001)^+ = 0$$

Otherwise,

$$\nabla_{\Theta}(000)^+ = 1$$

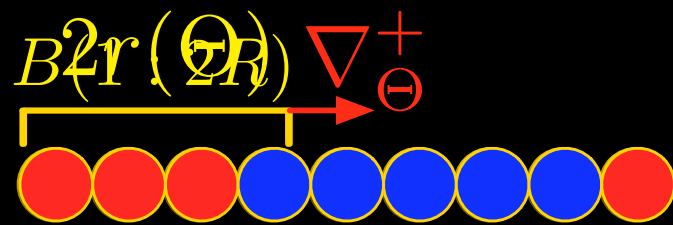
$$\nabla_{\Theta}(010)^+ = 0$$

$$\nabla_{\Theta}(b) = b(3)$$

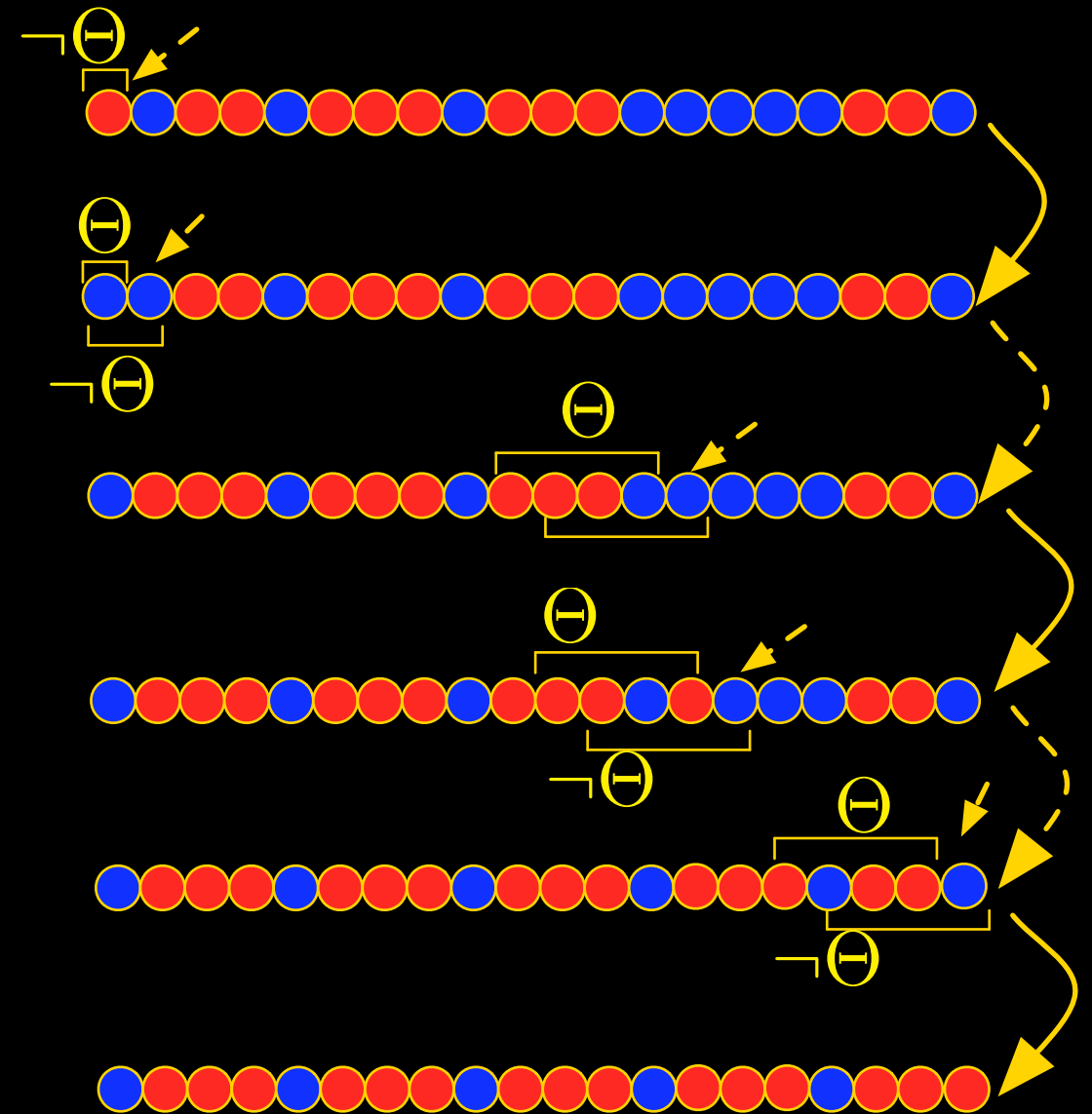
Designing Local Rules

Now simply define:

$$F(B) = \nabla_{\ominus}^+(B(1 : 2r))$$



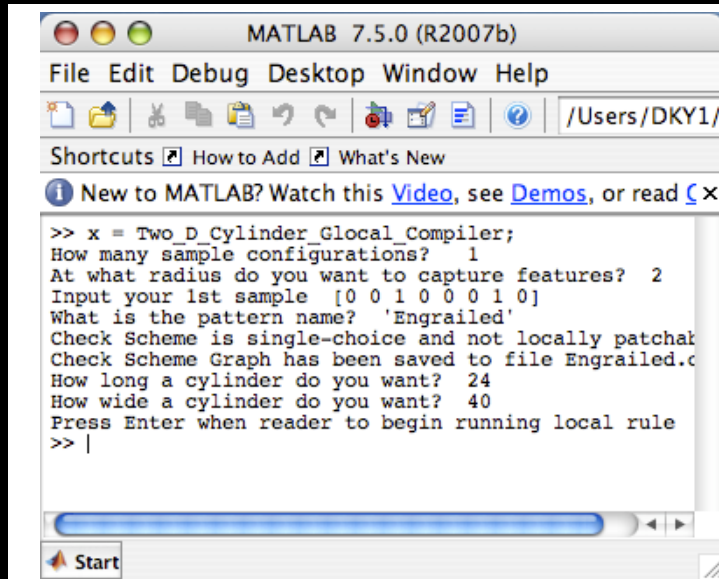
Gradient “spreads correctness.”



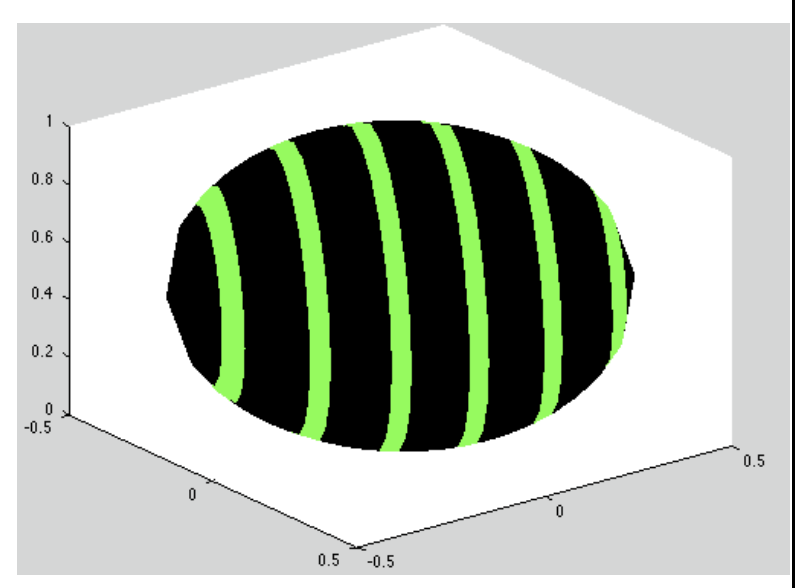
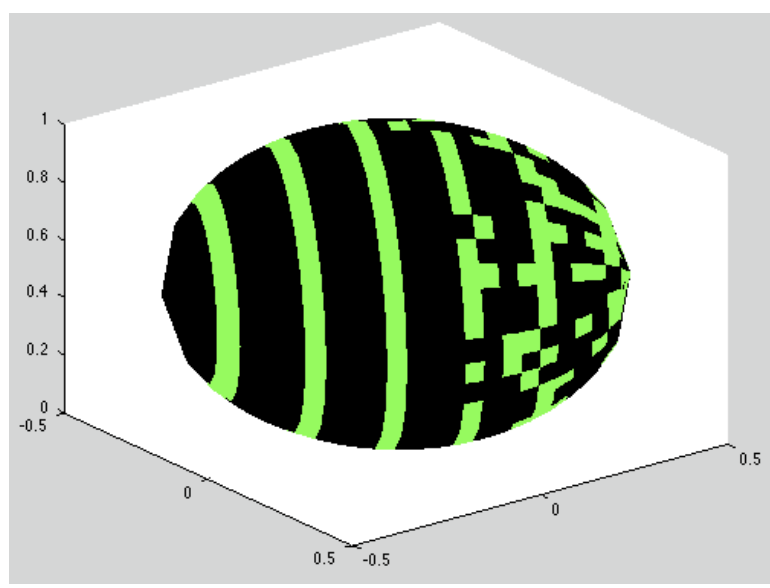
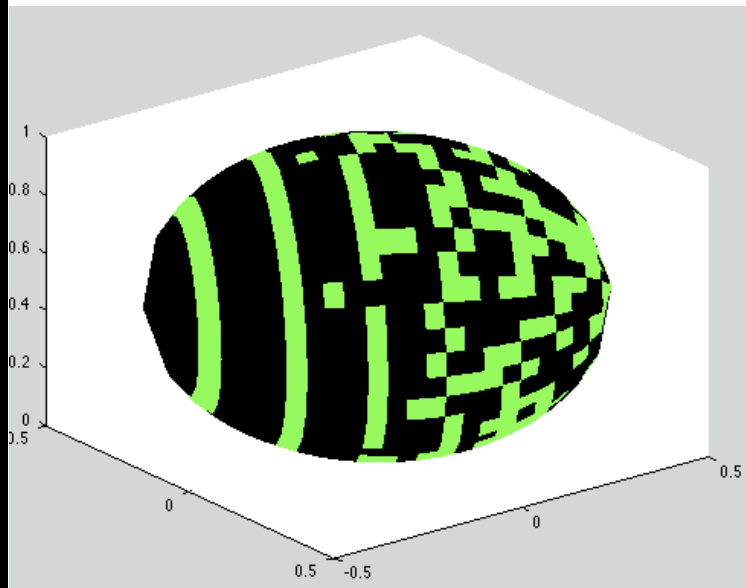
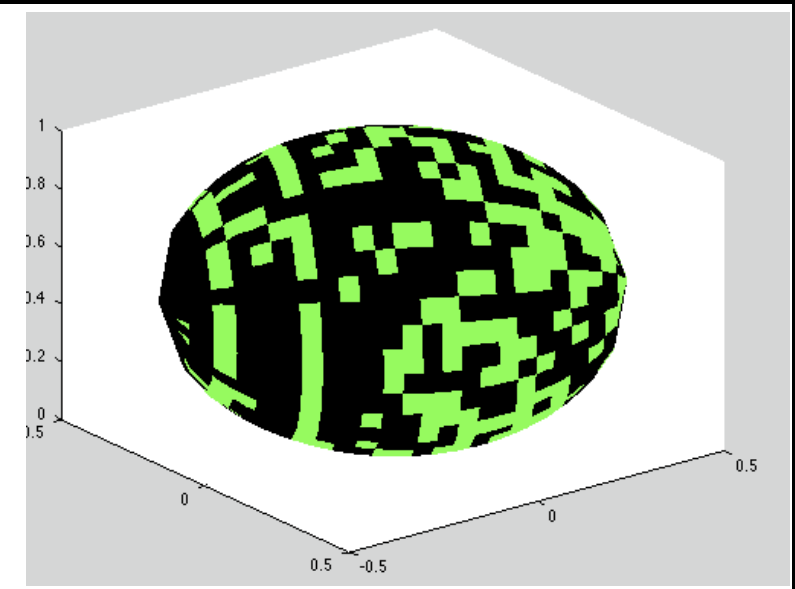
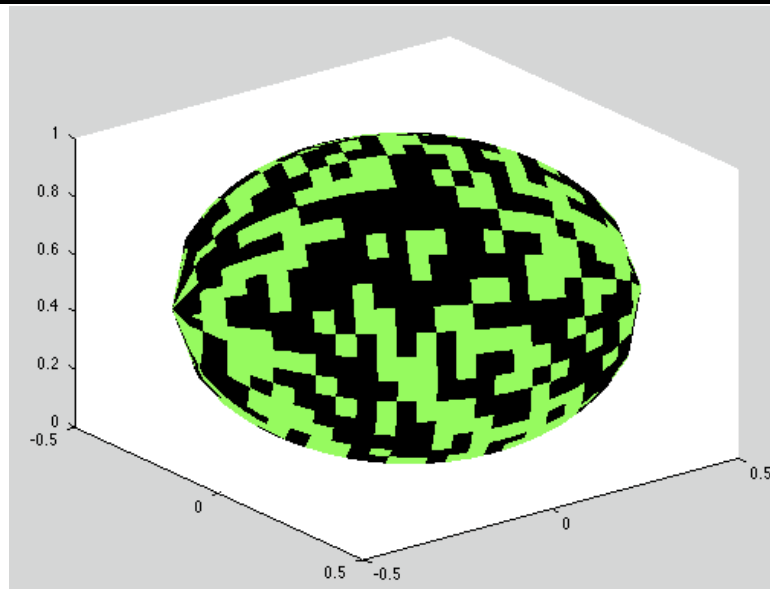
Gradient waves ... Multiple “waves” all at once in actuality

Not hard to implement in higher dimensions.

Designing Local Rules



```
>> x = Two_D_Cylinder_Glocal_Compiler;  
How many sample configurations? 1  
At what radius do you want to capture features? 2  
Input your 1st sample [0 0 1 0 0 0 1 0]  
What is the pattern name? 'Engrailed'  
Check Scheme is single-choice and not locally patchable  
Check Scheme Graph has been saved to file Engrailed.c  
How long a cylinder do you want? 24  
How wide a cylinder do you want? 40  
Press Enter when reader to begin running local rule  
>> |
```



Resulting rule is 100% robust to:

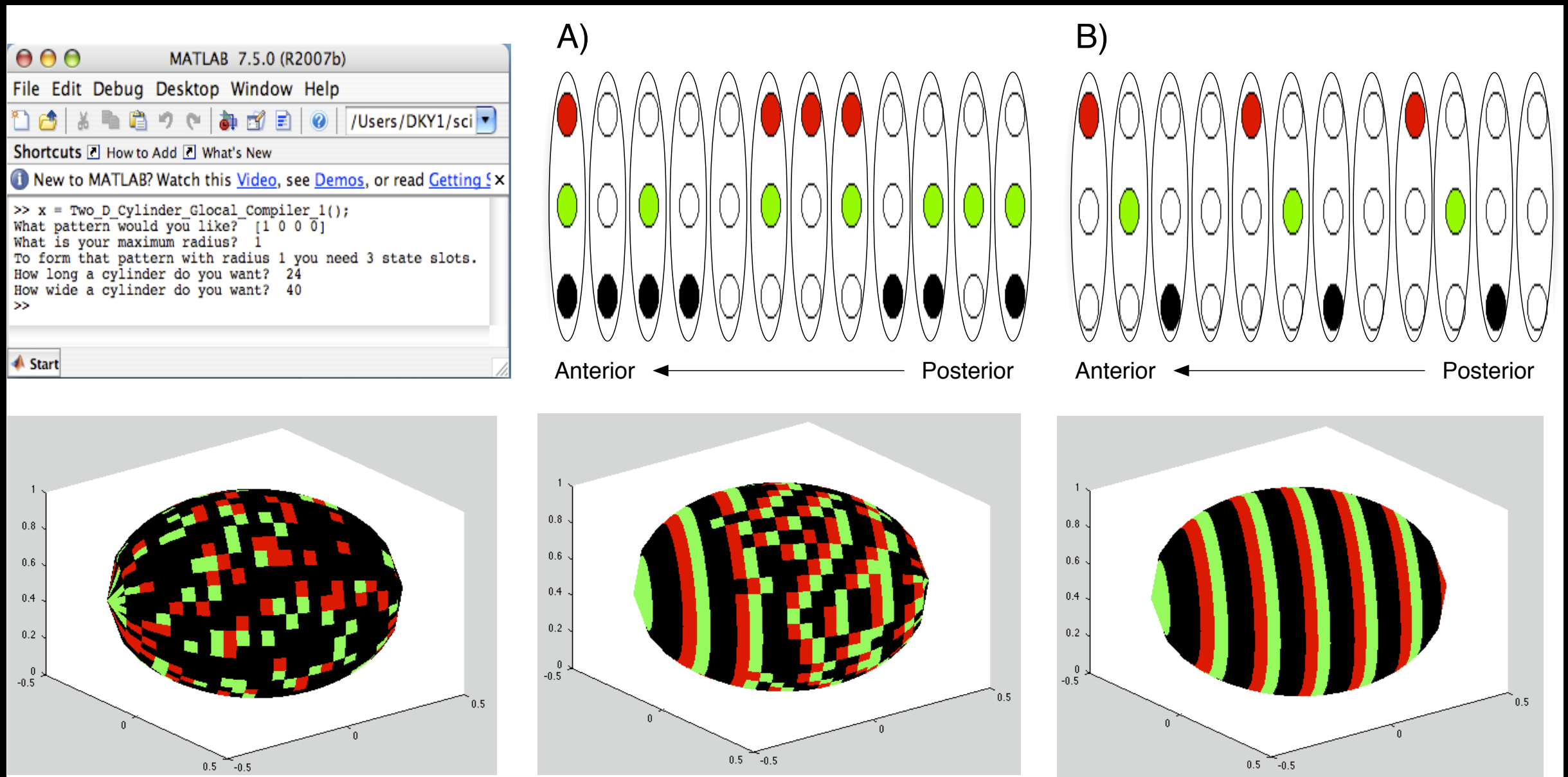
- Initial condition perturbations.
- Timing issues.

Designing Local Rules

But: the rule to solve a repeat pattern of size $|q|$ takes a radius of $|q|$.

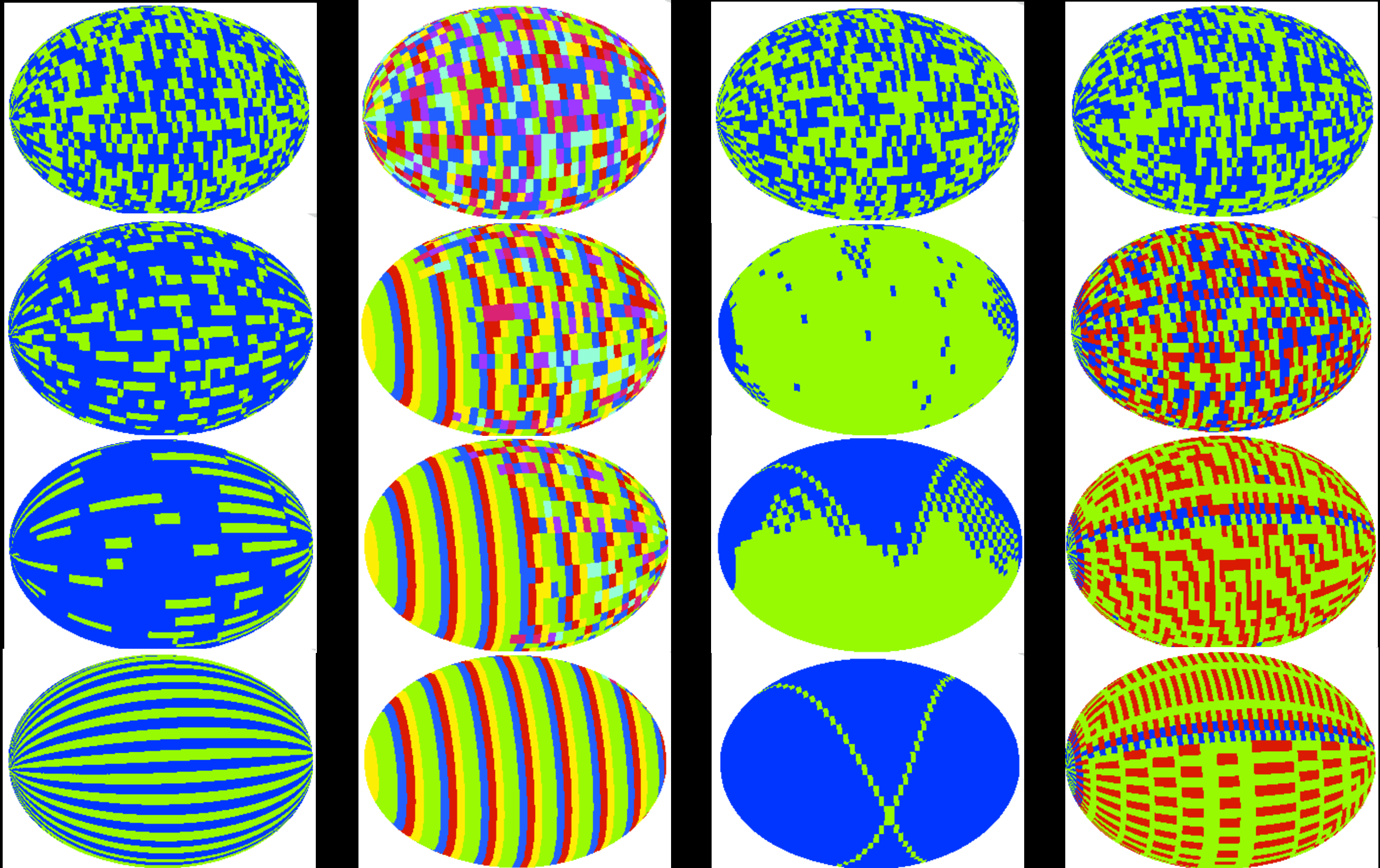
Can run a radius-minimization algorithm.

And then, couple in the radius/state tradeoff.

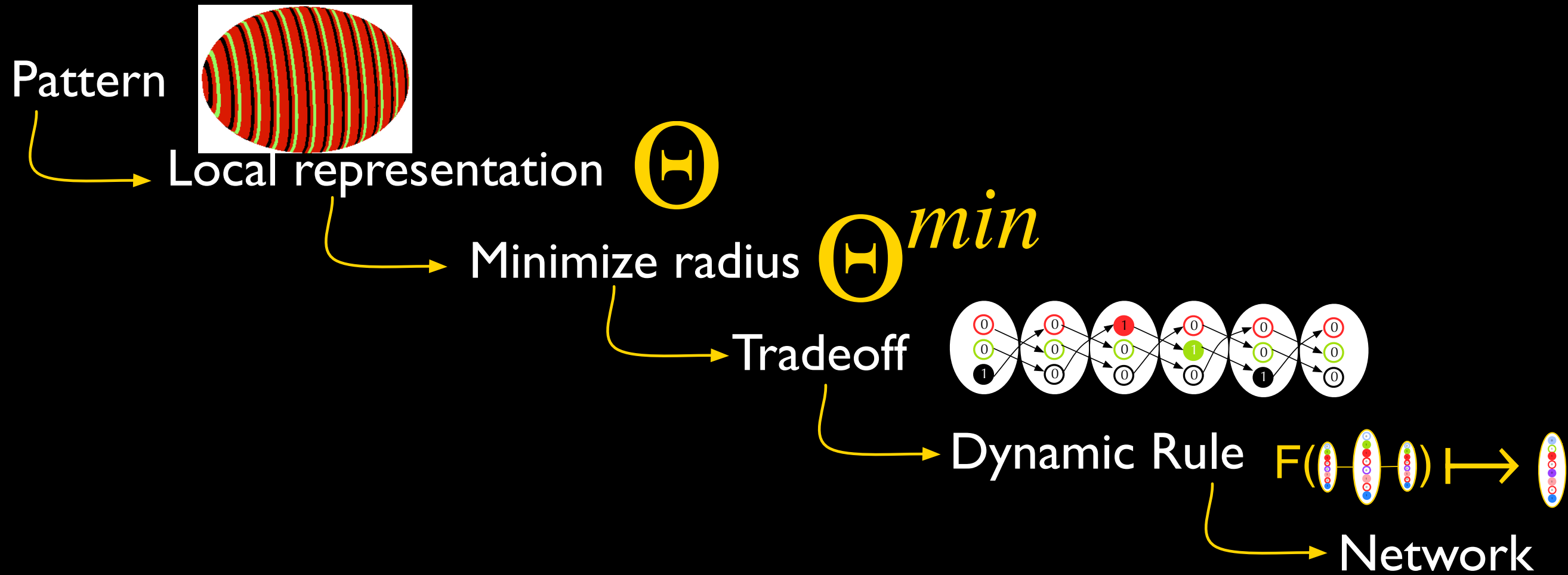


Designing Local Rules

Similar principles can be applied to develop a language for building a diverse array of patterns.



Designing Local Rules



???

Designing Local Rules

- Some VERY simple ideas in multi-cellular synthetic biology *might* be ``understandable'' (or at any rate, imagineable) and connectable to cellular programs
- Is anything here doable? even remotely?
- What is the simplest system that could possibly exploit some of these ideas?
- What I'd really like to explore is evolution.